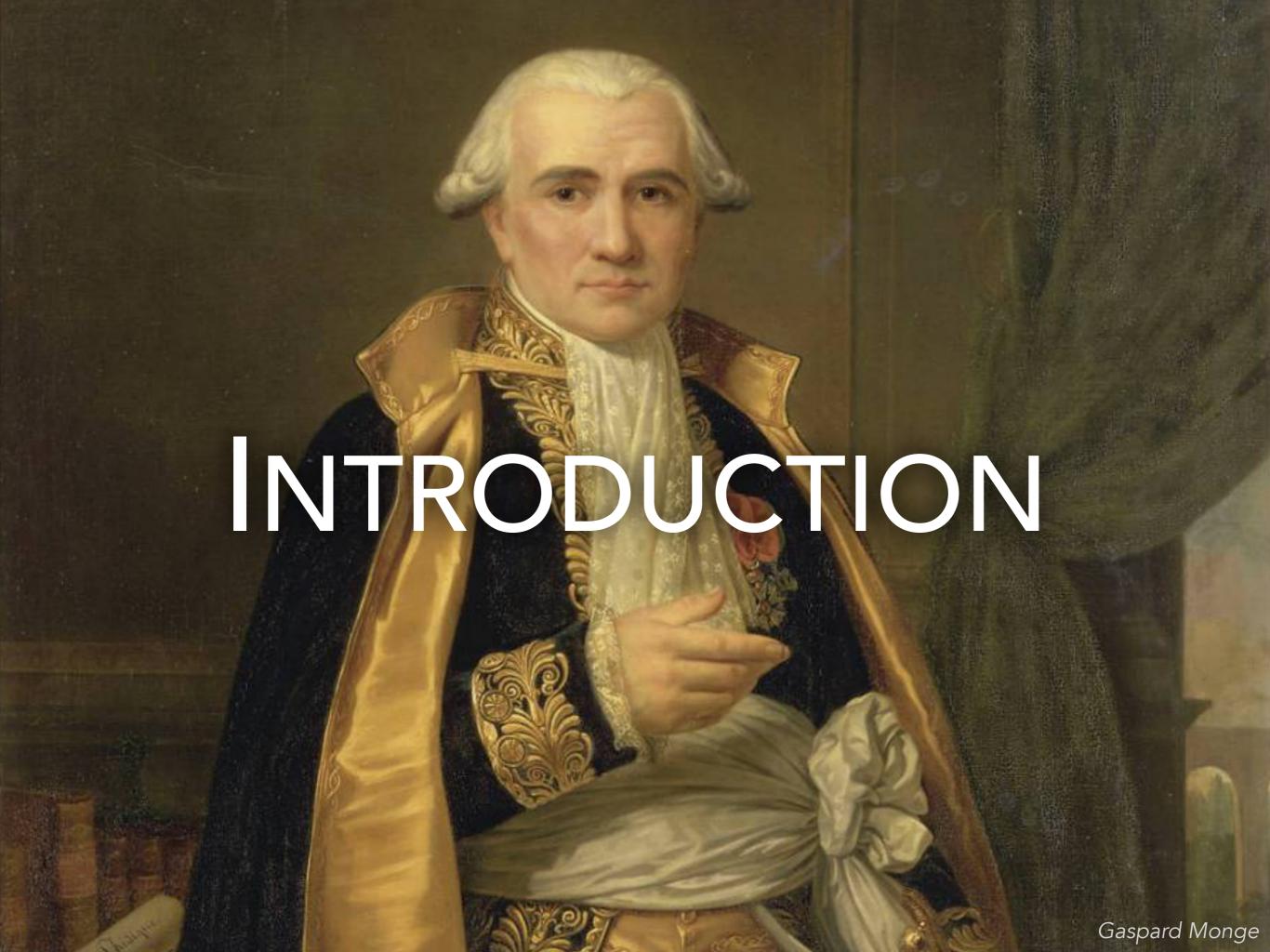
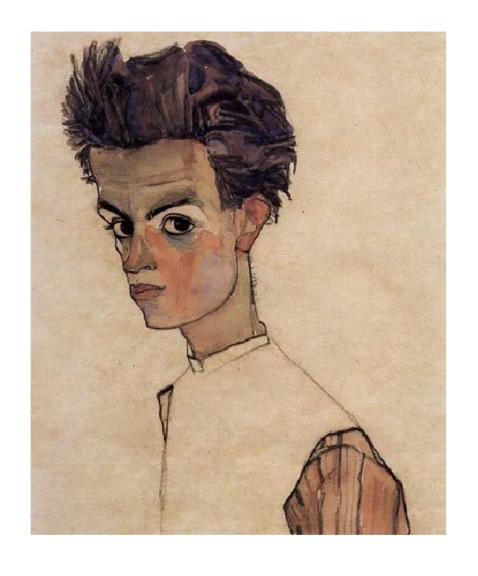
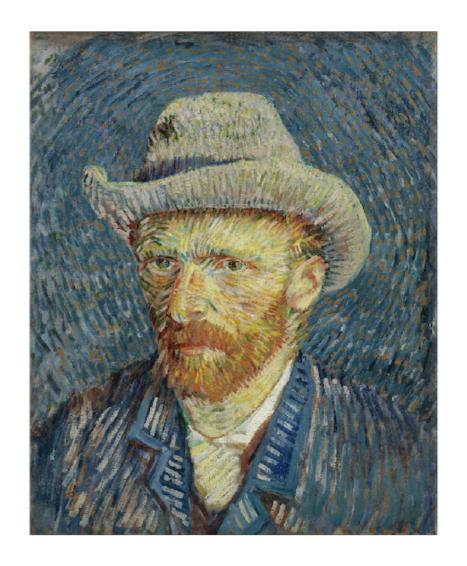
Regularity as Regularization: Smooth and Strongly Convex Brenier Potentials in Optimal Transport

F-P. PATY A. D'ASPREMONT M. CUTURI











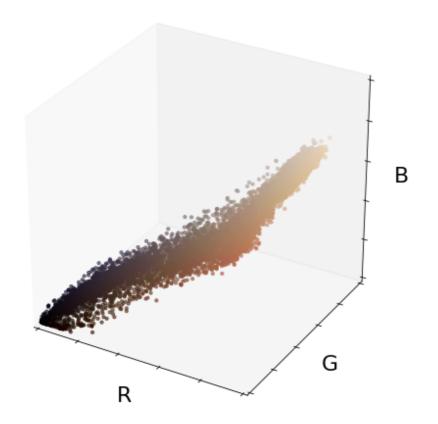
Color Transfer Map

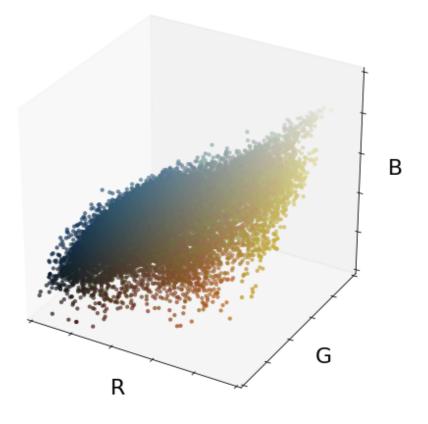




Color Transfer Map



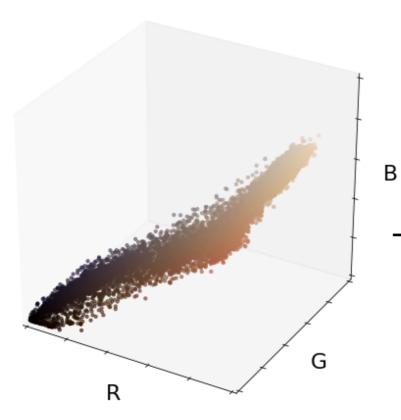




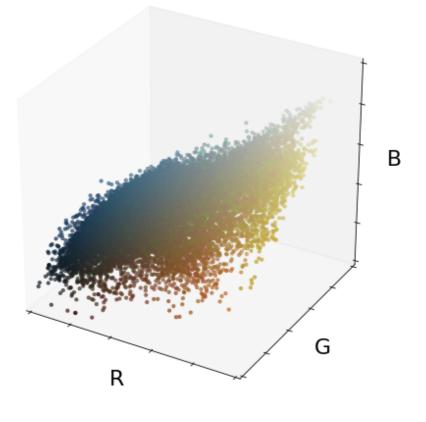


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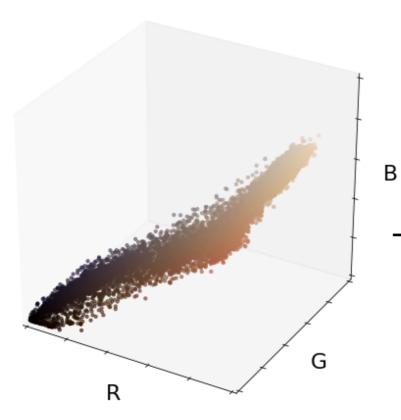
Matching



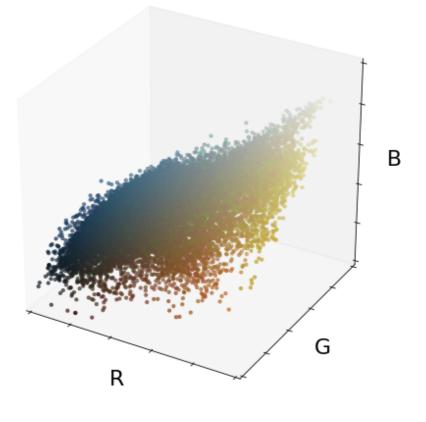


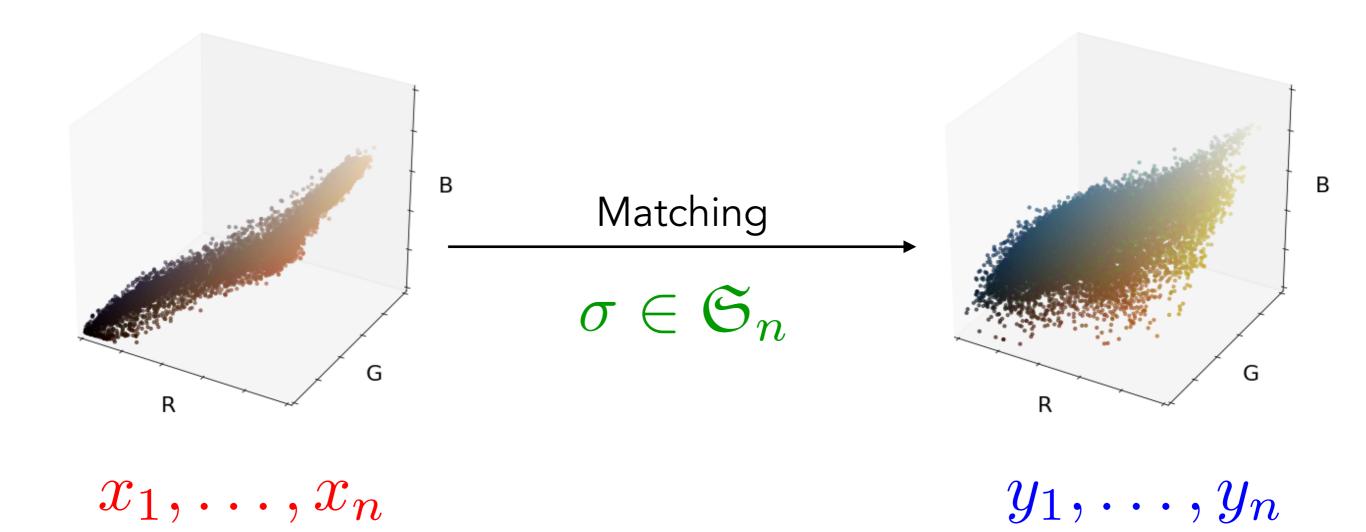
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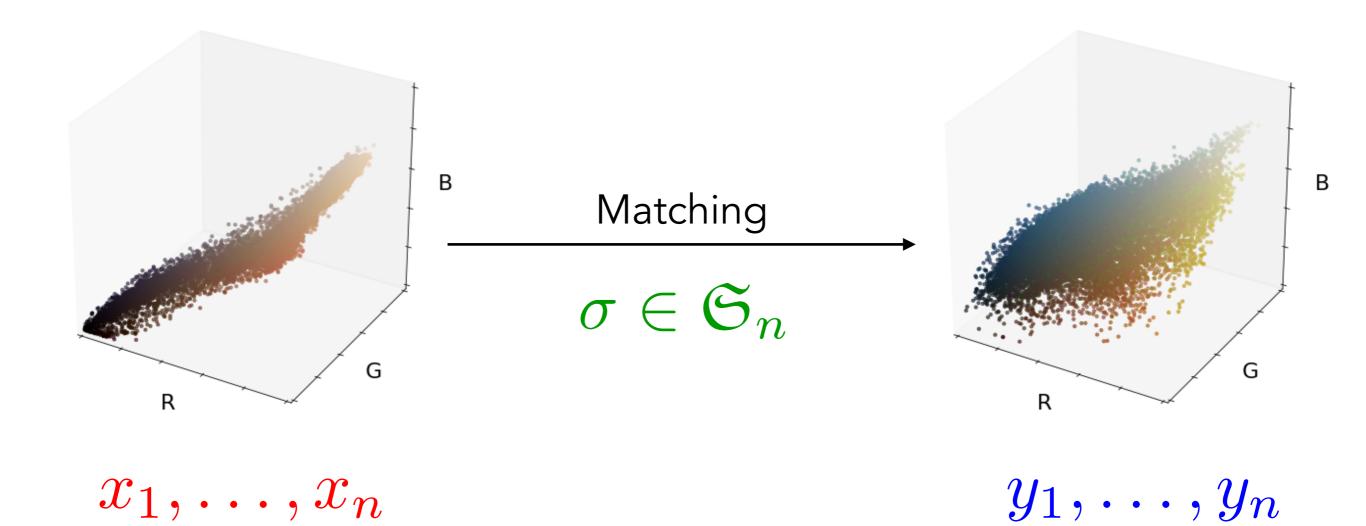


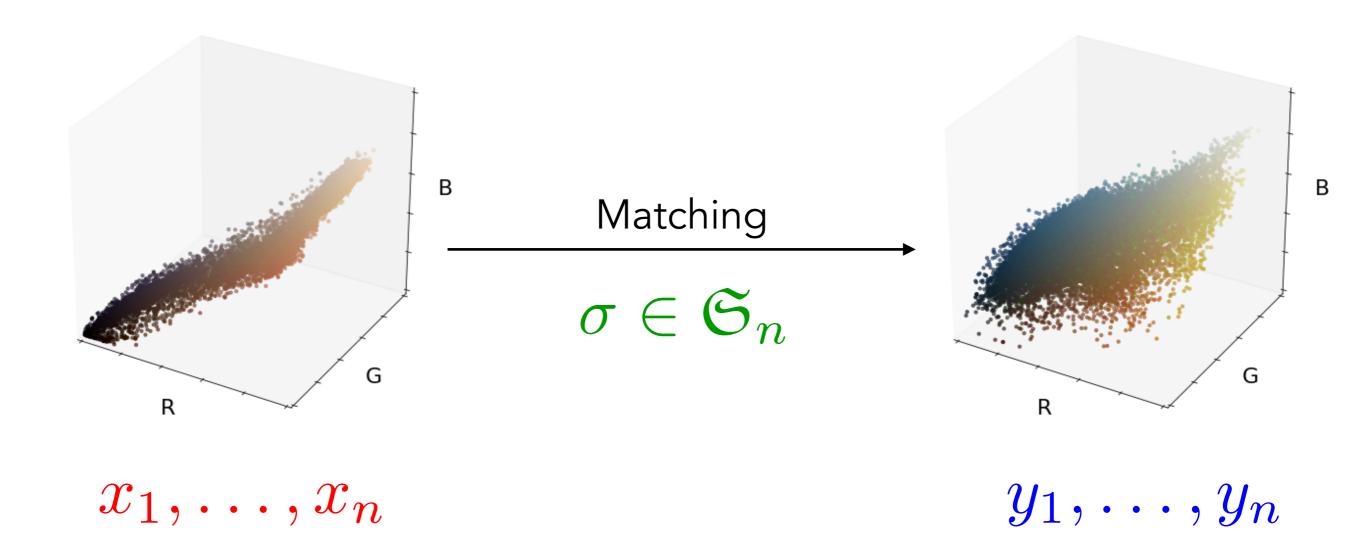


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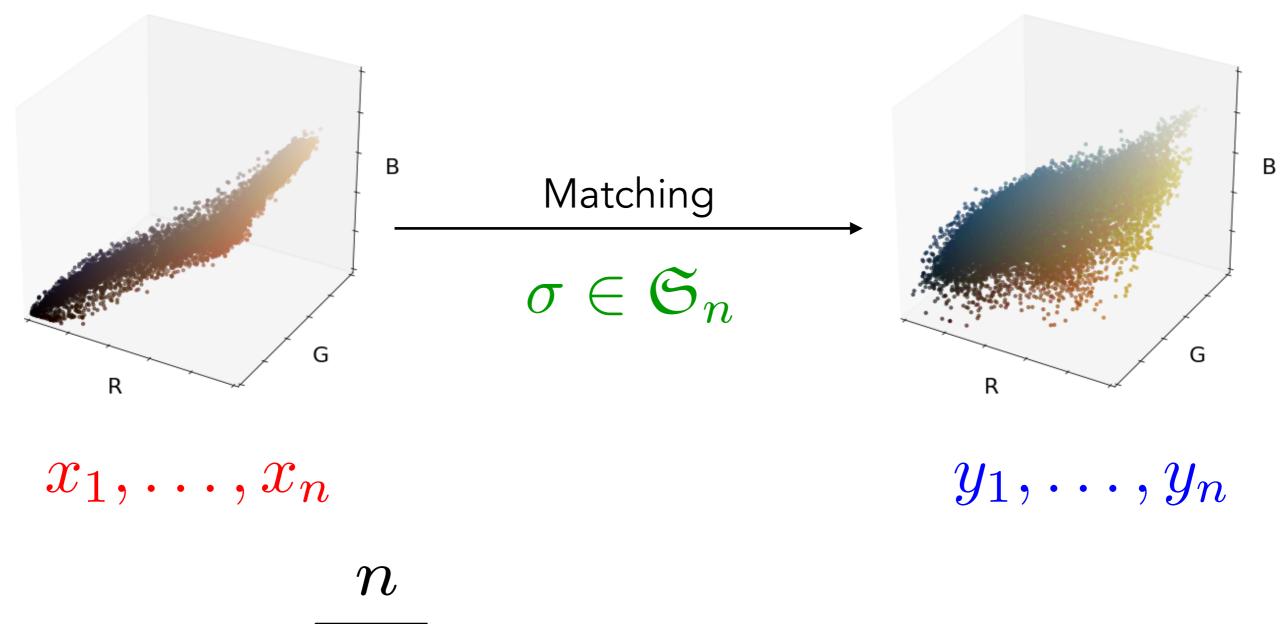




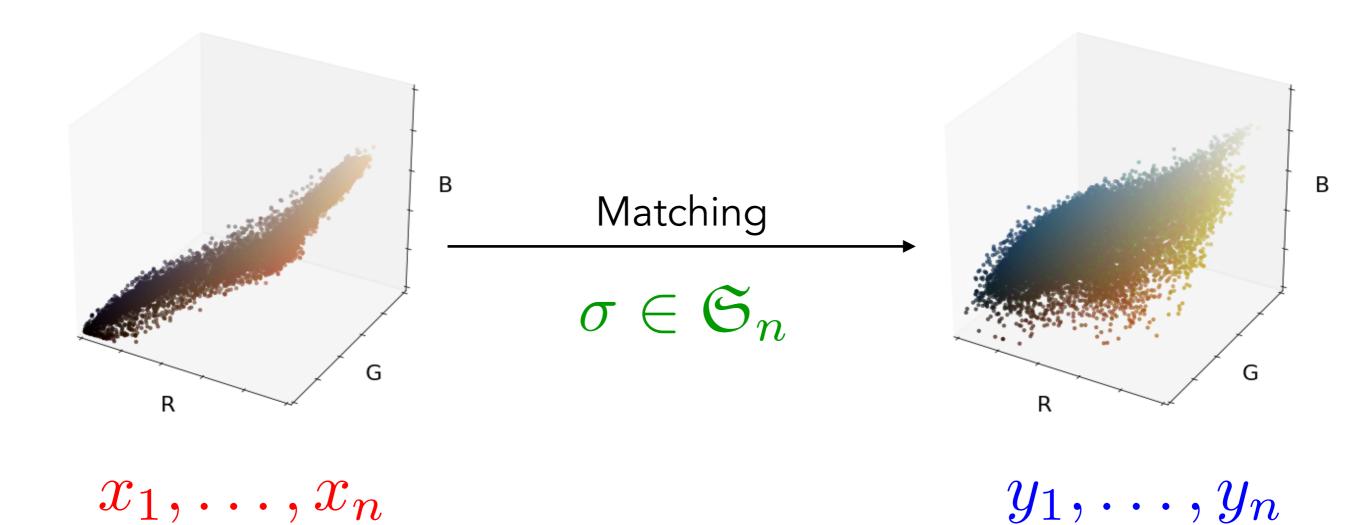




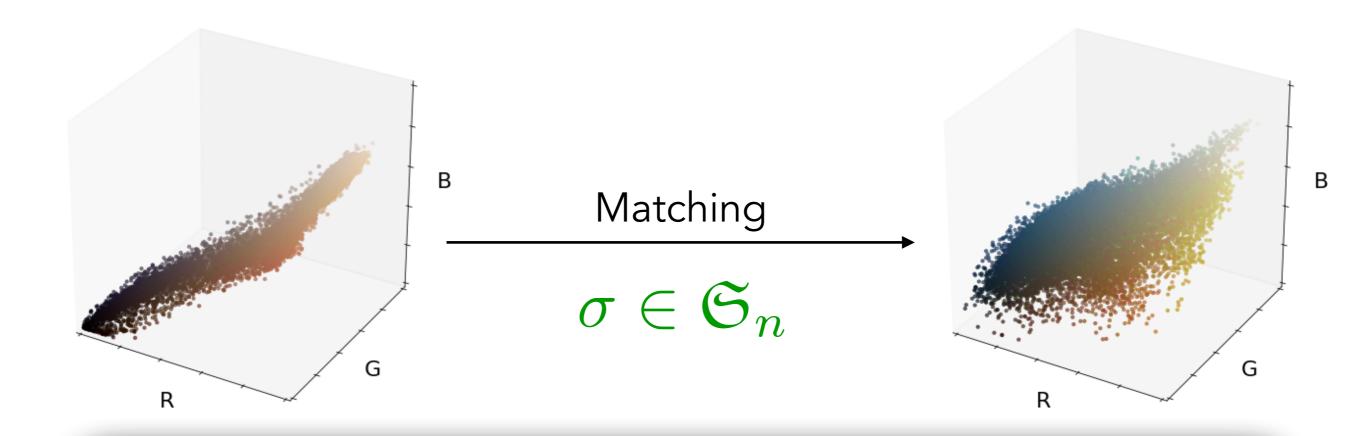
$$\|x_i-y_{\sigma(i)}\|^2$$



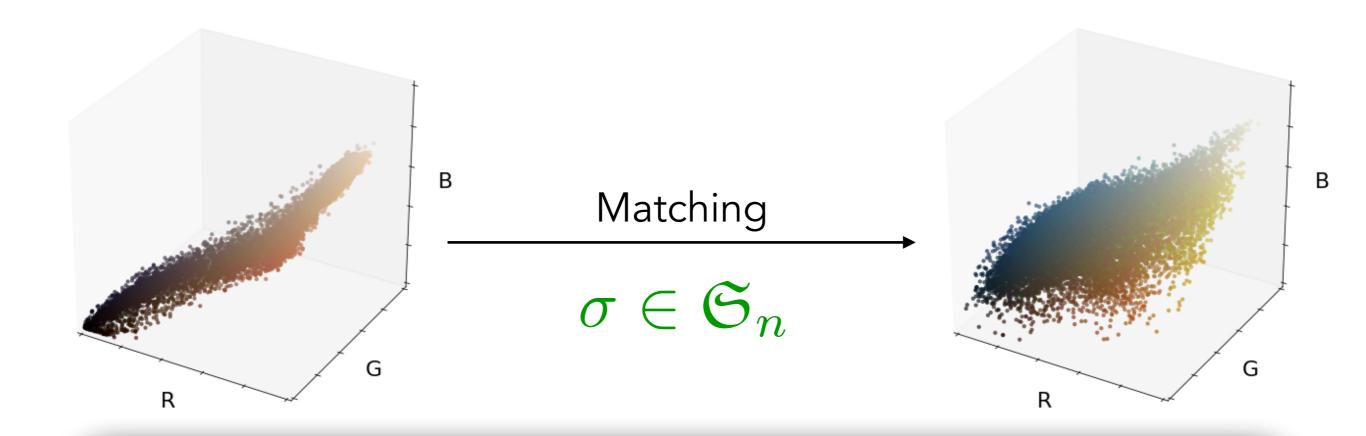
$$\sum_{i=1}^{n} \|x_i - y_{\sigma(i)}\|^2$$



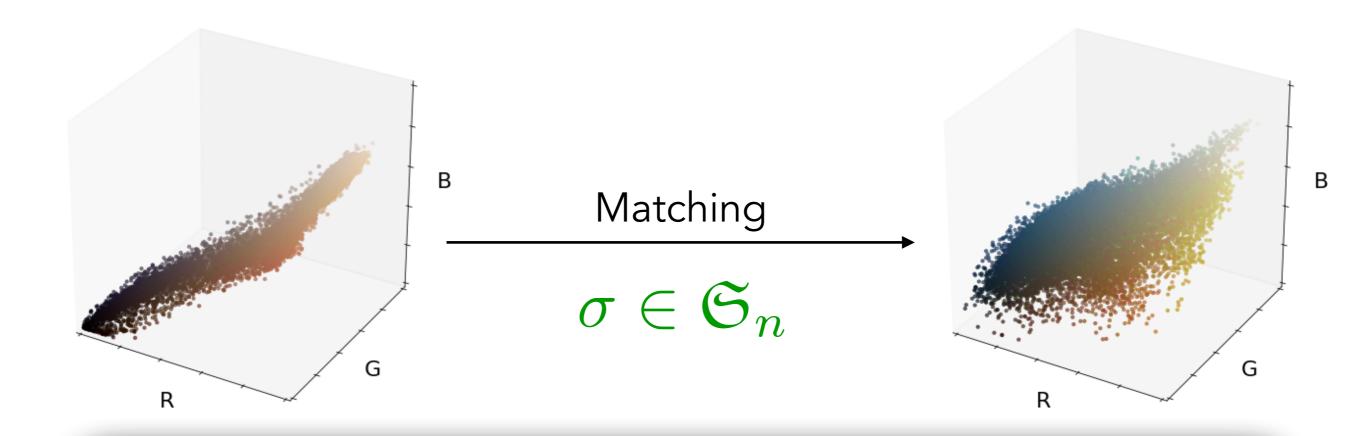
$$\min_{\sigma \in \mathfrak{S}_n} \sum_{i=1}^n \| \boldsymbol{x}_i - \boldsymbol{y}_{\sigma(i)} \|^2$$



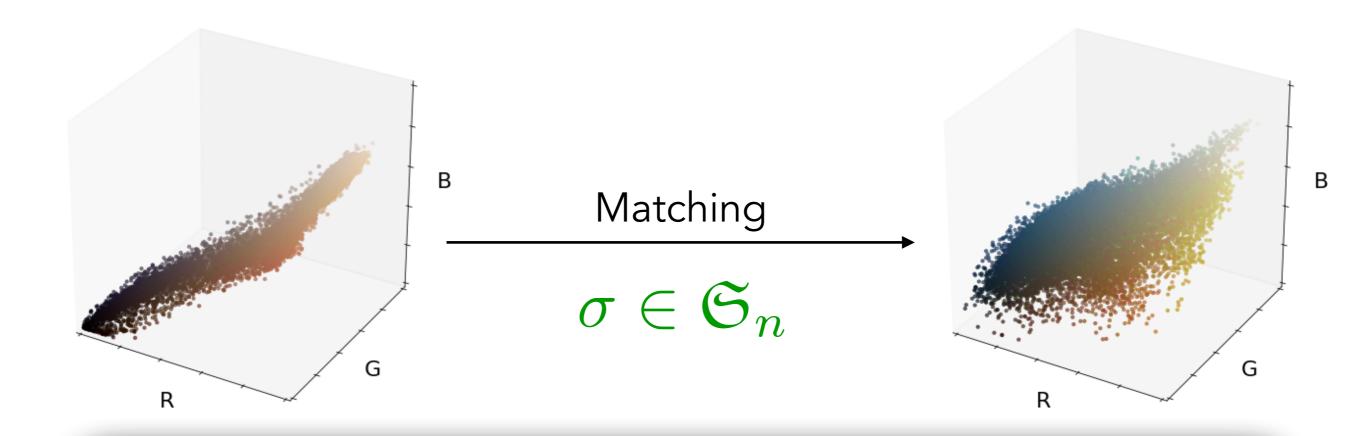
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- (i) How to handle repeated points?
- (ii) How to handle different numbers of points?
- (iii) How to compute this combinatorial problem?



$$\min_{\sigma \in \mathfrak{S}_n} \sum_{i=1}^n \| \boldsymbol{x}_i - \boldsymbol{y}_{\sigma(i)} \|^2$$

$$\min_{\sigma \in \mathfrak{S}_n} \sum_{i=1}^n \sum_{j=1}^n ||\mathbf{x}_i - \mathbf{y}_j||^2 \, \mathbb{1}_{\sigma(i)=j}$$

$$\min_{P \in \mathfrak{P}_n} \sum_{i=1}^n \sum_{j=1}^n ||x_i - y_j||^2 P_{ij}$$

$$\mathfrak{P}_n = \{ P \in \mathbb{R}^{n \times n} \text{ permutation matrix} \}$$

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If $\mathbf{a} \in \mathbb{R}^n$, $\mathbf{b} \in \mathbb{R}^m$ are probability weights, we define the associated **transportation polytope**:

$$\min_{P \in \mathfrak{P}_n} \sum_{i=1}^n \sum_{j=1}^n ||\mathbf{x}_i - \mathbf{y}_j||^2 P_{ij}$$
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If $\mathbf{a} \in \mathbb{R}^n$, $\mathbf{b} \in \mathbb{R}^m$ are probability weights, we define the associated **transportation polytope**:

$$\mathfrak{U}(\mathbf{a}, \mathbf{b}) = \{ P \in \mathbb{R}_+^{n \times m} \mid P \mathbb{1}_m = \mathbf{a}, P^\top \mathbb{1}_n = \mathbf{b} \}$$

Discrete Kantorovitch Problem

$$W_2^2(\mu, \nu) = \min_{P \in \mathfrak{U}(\mathbf{a}, \mathbf{b})} \sum_{i=1}^n \sum_{j=1}^m \|\mathbf{x}_i - \mathbf{y}_j\|^2 P_{ij}$$

where
$$\mu = \sum_{i=1}^n \mathbf{a}_i \delta_{x_i}$$
 and $\nu = \sum_{j=1}^m \mathbf{b}_j \delta_{y_j}$ are probability measures

2-Wasserstein distance

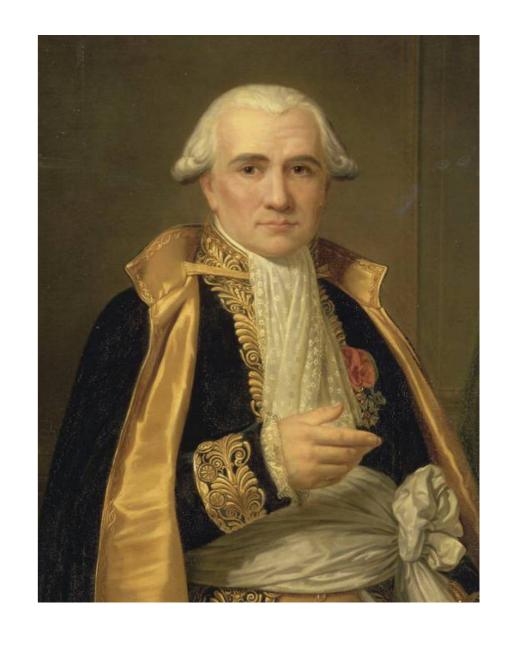
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In practice, one color should be mapped to exactly one color. In other words, we want to find a map

$$T: \mathbb{R}^d o \mathbb{R}^d$$

that is optimal in some sense.



Monge problem

$$\min_{\sigma \in \mathfrak{S}_n} \sum_{i=1}^n \| \mathbf{x}_i - \mathbf{y}_{\sigma(i)} \|^2$$

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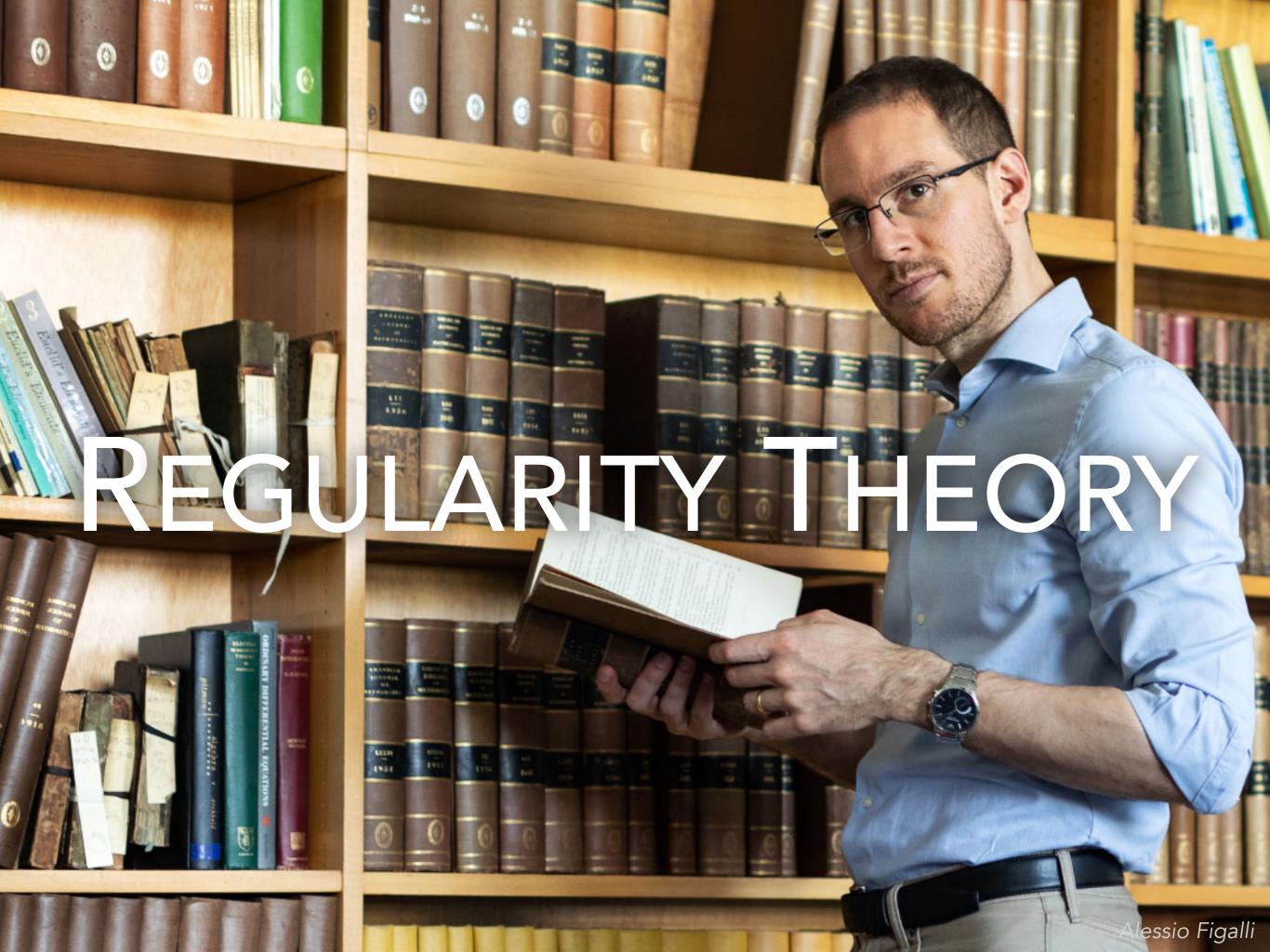
$$\inf_{T_{\sharp}\mu=\nu}\int \|x-T(x)\|^2 d\mu(x)$$

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$$X \sim \mu \Longrightarrow T(X) \sim \nu$$



Let μ and ν be two probability measures over \mathbb{R}^d .

$$\inf_{T_{\sharp}\mu=\nu}\int \|x-T(x)\|^2 d\mu(x)$$

When does the Monge problem admit a solution? What can be said about it?

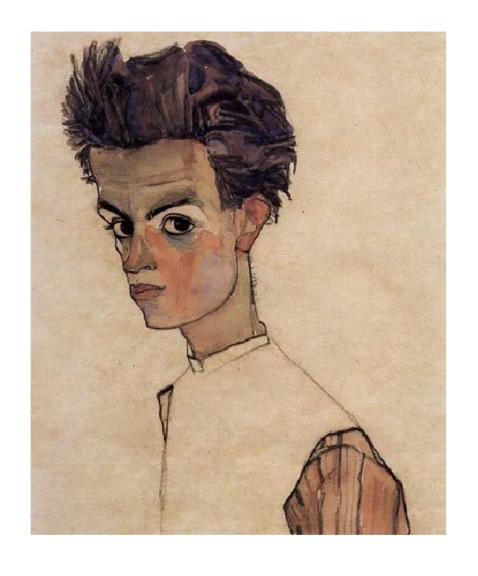
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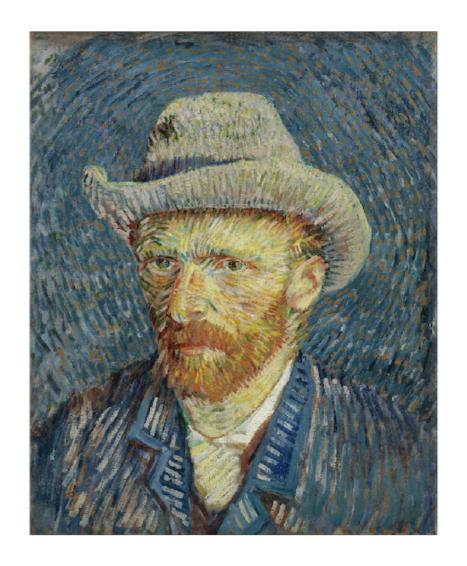
$$\inf_{T_{\sharp}\mu=\nu}\int \|\mathbf{x}-T(\mathbf{x})\|^2 d\mu(\mathbf{x})$$

Brenier Theorem

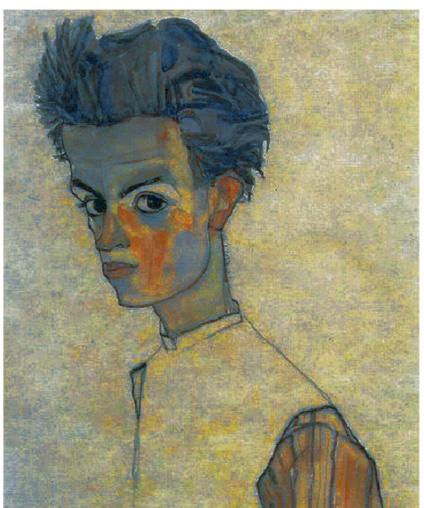
- 1. If μ is absolutely continuous with respect to the Lebesgue measure, the Monge problem admits a unique solution
- 2. If the Monge problem admits a solution T, then there exists a convex function f, called a **Brenier potential**, s.t.

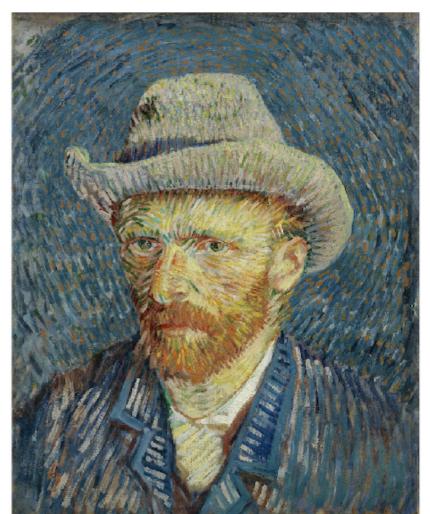
$$T = \nabla f$$



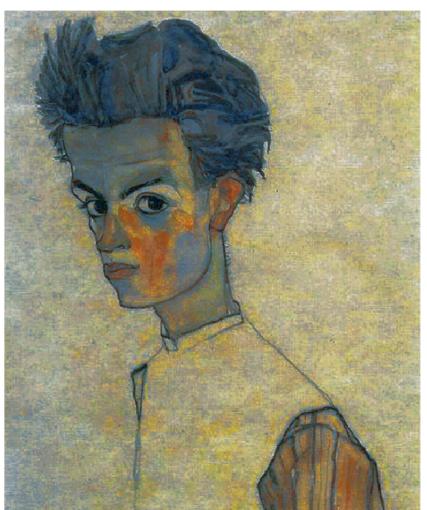


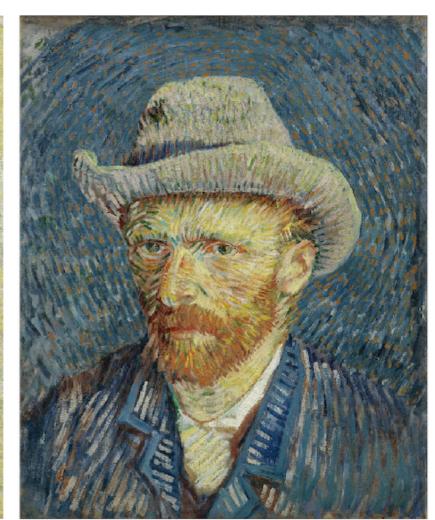








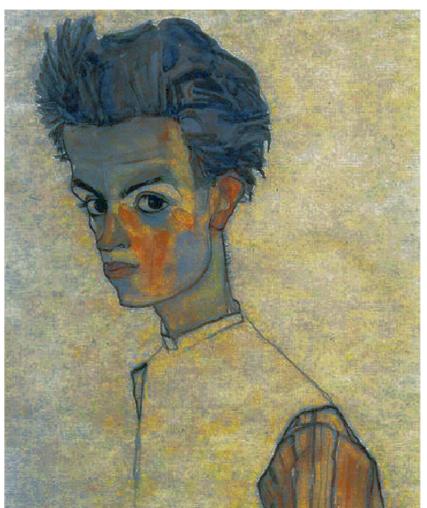


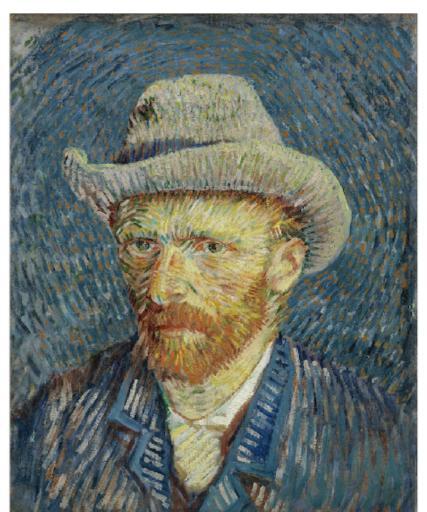


Instead of finding assumptions under which the optimal map exists and exhibits some regularity, we will enforce such existence/regularity directly in the OT problem.

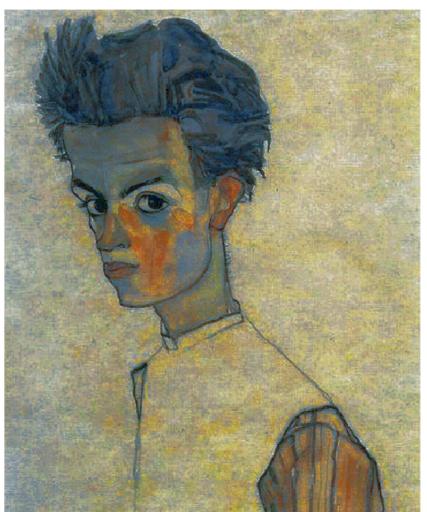


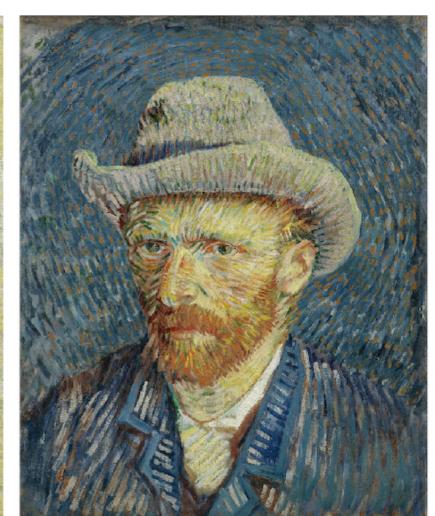






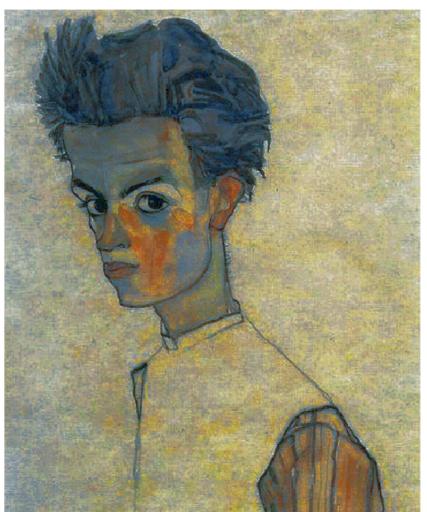


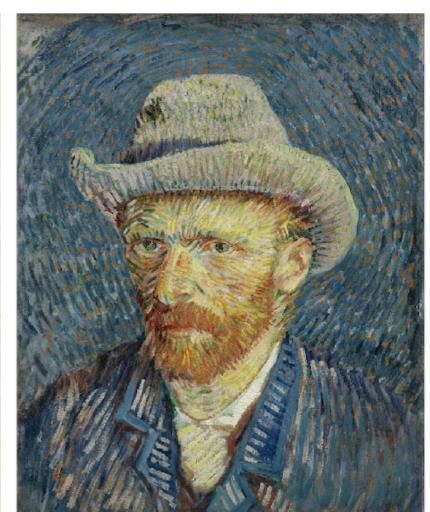




$$\ell \|x - y\| \le \|\nabla f(x) - \nabla f(y)\| \le L\|x - y\|$$



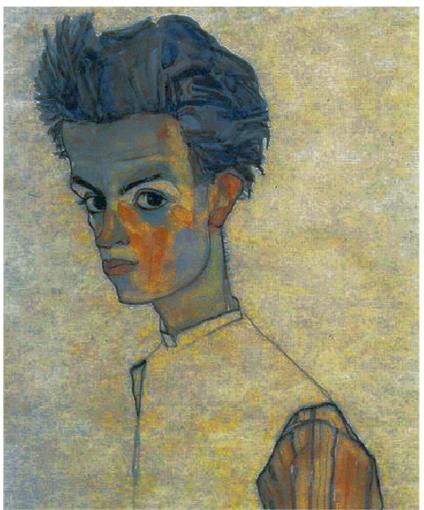


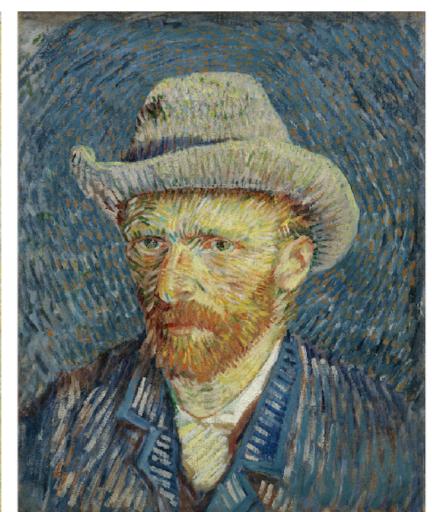


$$\ell \|x - y\| \le \|\nabla f(x) - \nabla f(y)\| \le L\|x - y\|$$

We ask that $\,T=
abla f\,$ is a bi-Lipschitz map



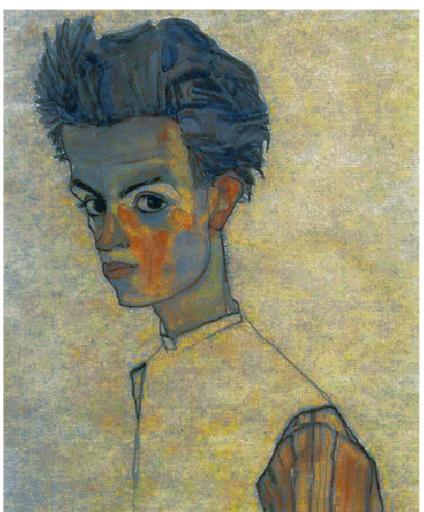


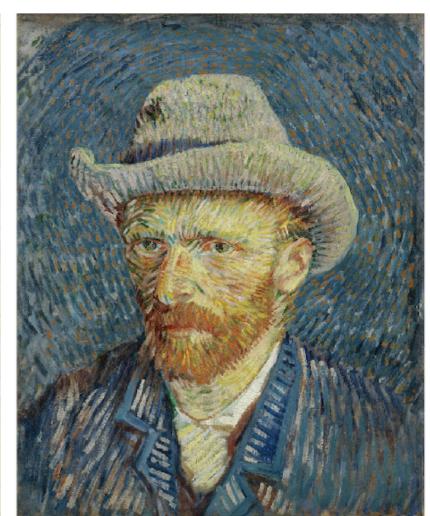


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We ask that f is **smooth** and **strongly convex**







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We ask that f is **smooth** and **strongly convex**

$$f \in \mathcal{F}_{\ell,L}$$

But there may not even such a regular f that is admissible for the Monge problem, i.e. such that $(\nabla f)_{\sharp}\mu = \nu$.

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Instead, we will try to best approximate ν as a push-forward of μ through a regular map:

$$\min_{f \in \mathcal{F}_{\ell,L}} W_2 \left[\nabla f_{\sharp \mu}, \nu \right]$$

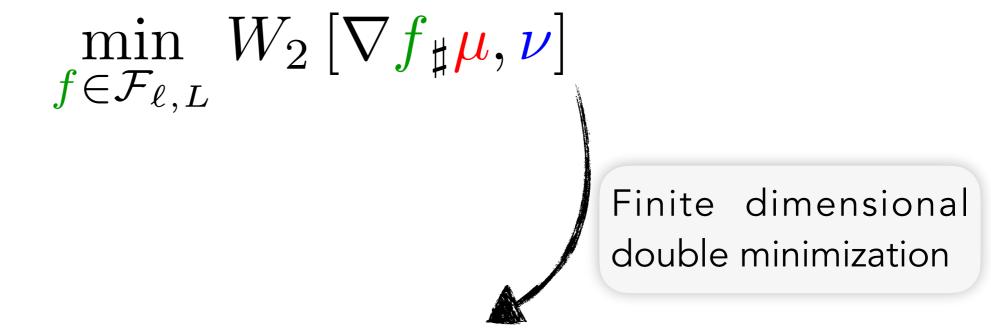
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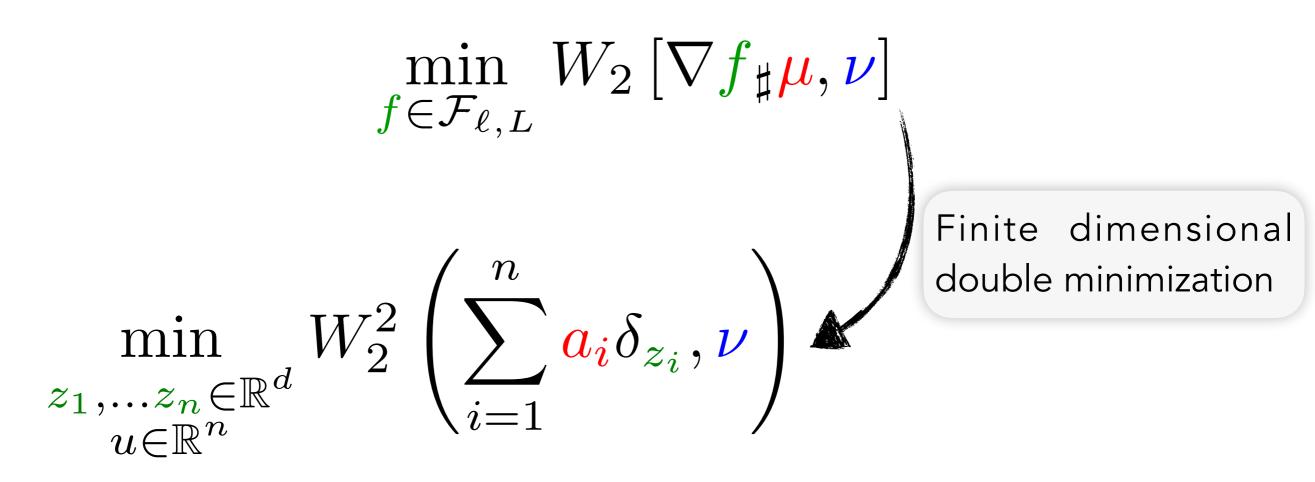
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Smooth and Strong Convex Brenier Potentials

$$\min_{f \in \mathcal{F}_{\ell,L}} W_2 \left[\nabla f_{\sharp} \mu, \nu \right]$$





$$\min_{f \in \mathcal{F}_{\ell,L}} W_2 \left[\nabla f_{\sharp \mu}, \nu \right]$$
 Finite dimensional double minimization
$$\min_{z_1, \dots z_n \in \mathbb{R}^d} W_2^2 \left(\sum_{i=1}^n a_i \delta_{z_i}, \nu \right)$$

$$u_{i} \geq u_{j} + \langle z_{j}, \mathbf{x}_{i} - \mathbf{x}_{j} \rangle$$

$$+ \frac{1}{2(1 - \ell/L)} \left(\frac{1}{L} \|z_{i} - z_{j}\|^{2} + \ell \|\mathbf{x}_{i} - \mathbf{x}_{j}\|^{2} - 2\frac{\ell}{L} \langle z_{j} - z_{i}, \mathbf{x}_{j} - \mathbf{x}_{i} \rangle \right)$$

$$x_1,\ldots,x_n\sim\mu$$

$$\hat{\boldsymbol{\mu}}_{\boldsymbol{n}} = \frac{1}{n} \sum_{i=1}^{n} \delta_{\boldsymbol{x}_{i}}$$

$$y_1,\ldots,y_n\sim \nu$$

$$\hat{\mathbf{v}}_{n} = \frac{1}{n} \sum_{i=1}^{n} \delta_{\mathbf{y}_{i}}$$

$$egin{aligned} oldsymbol{x}_1, \dots, oldsymbol{x}_n &\sim \mu & y_1, \dots, y_n \sim \nu \ \hat{oldsymbol{\mu}}_n &= rac{1}{n} \sum_{i=1}^n \delta_{oldsymbol{x}_i} & \hat{oldsymbol{
u}}_n &= rac{1}{n} \sum_{i=1}^n \delta_{oldsymbol{y}_i} \ f^\star \in rg \min W_2 \left[
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 $f^* \in \arg\min W_2\left[\nabla f_{\sharp}\hat{\mu}_n, \hat{\nu}_n\right]$

 $f \in \mathcal{F}_{\ell,L}$

Solved by alternating minimization on f and Wasserstein computation

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We can easily compute the map on any new point ${\mathcal X}$ by solving a cheap QCQP

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Solved by alternating minimization $f \in \mathcal{F}_{\ell,L}$ on f and Wasserstein computation

We can easily compute the map on any new point \boldsymbol{x} by solving a cheap QCQP

$$\min_{v \in \mathbb{R}, g \in \mathbb{R}^d} v$$
s.t. $\forall i, v \geq u_i + \langle z_i^{\star}, \mathbf{x} - \mathbf{x_i} \rangle$

$$+ \frac{1}{2(1 - \ell/L)} \left(\frac{1}{L} \|g - z_i^{\star}\|^2 + \ell \|\mathbf{x} - \mathbf{x_i}\|^2 - 2\frac{\ell}{L} \langle z_i^{\star} - g, \mathbf{x_i} - \mathbf{x} \rangle \right)$$

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This defines an estimator ∇f^{\star} of the optimal transport map sending μ to ν

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We define the SSNB estimator as a plug-in:

$$x_1,\dots,x_n\sim \mu \qquad \qquad y_1,\dots,y_n\sim \nu$$

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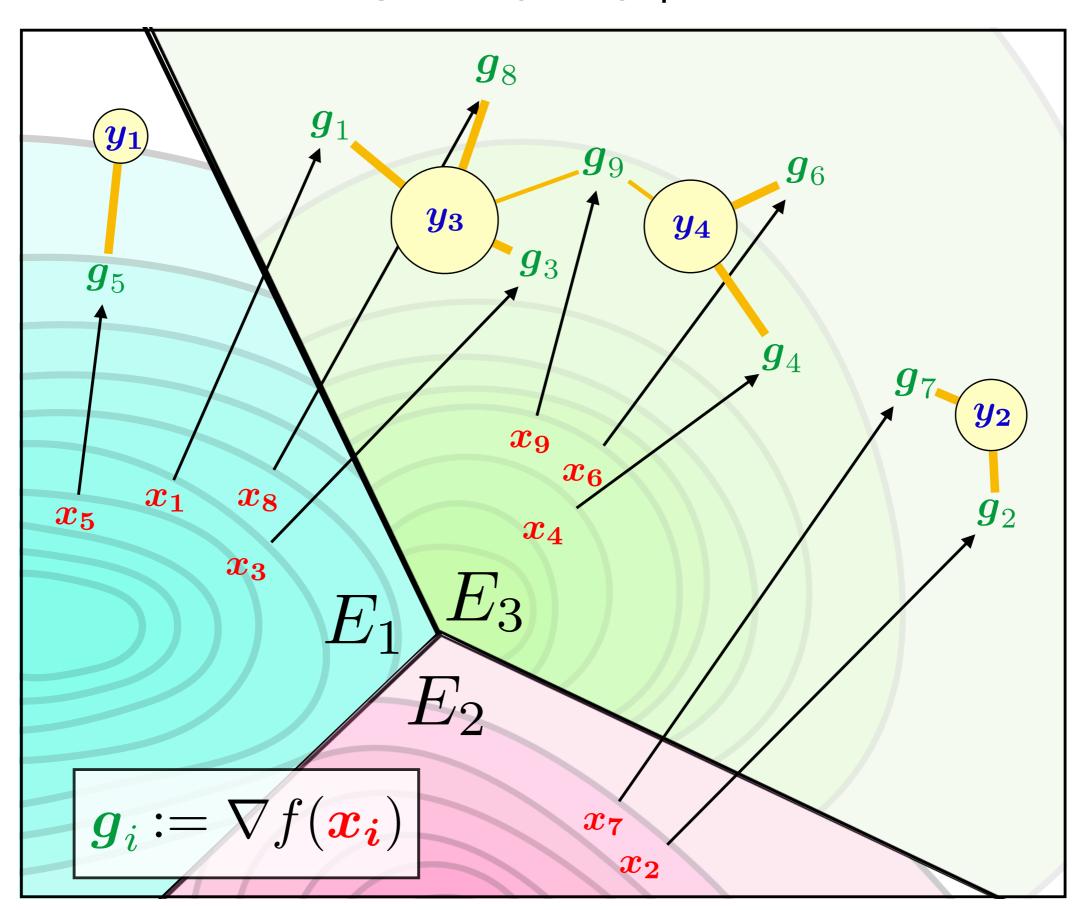
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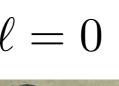
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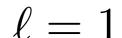
Regularity "by part"

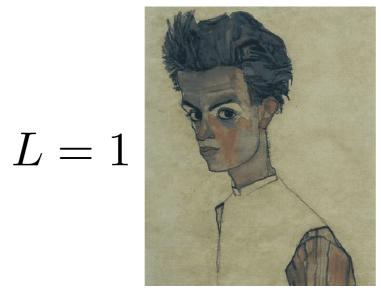






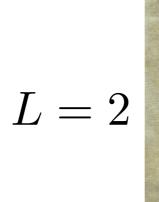
$$\ell = 0 \qquad \ell = 0.5 \qquad \ell = 1$$











L=5







