

Regularizing Optimal Transport Using Regularity Theory

Learning meets Astrophysics

January 17, 2020

FRANÇOIS-PIERRE PATY

francoispierrepaty.github.io

*Based on a joint work with
Alexandre d'Aspremont and
Marco Cuturi (AISTATS 2020)*

ENSAE



IP PARIS



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A portrait of Gaspard Monge, a French mathematician and physicist. He is depicted from the chest up, wearing a dark blue coat with elaborate gold embroidery on the collar and cuffs. He has white powdered hair and is looking slightly to the right. The background is dark and indistinct.

INTRODUCTION



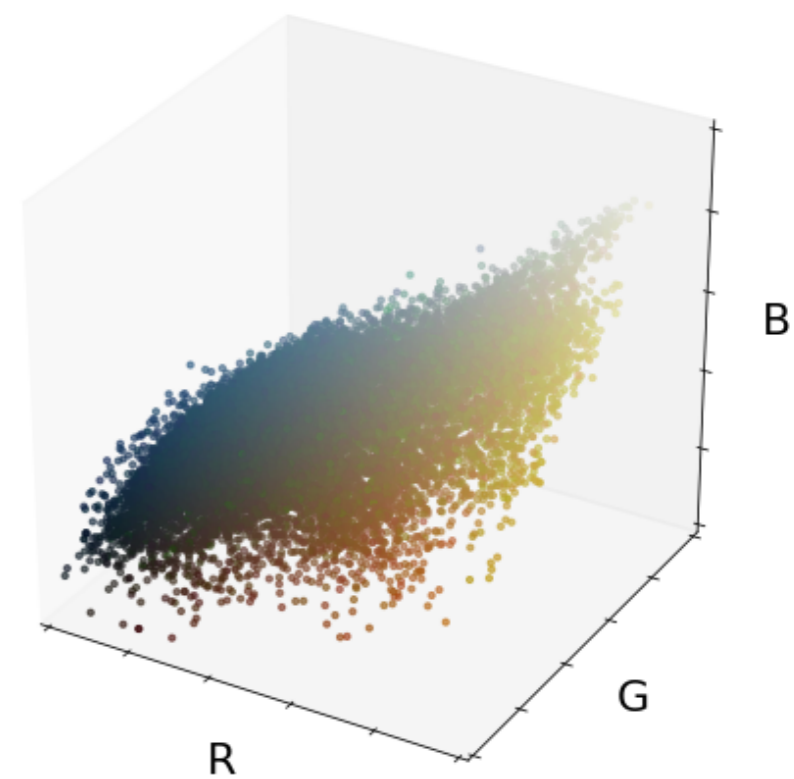
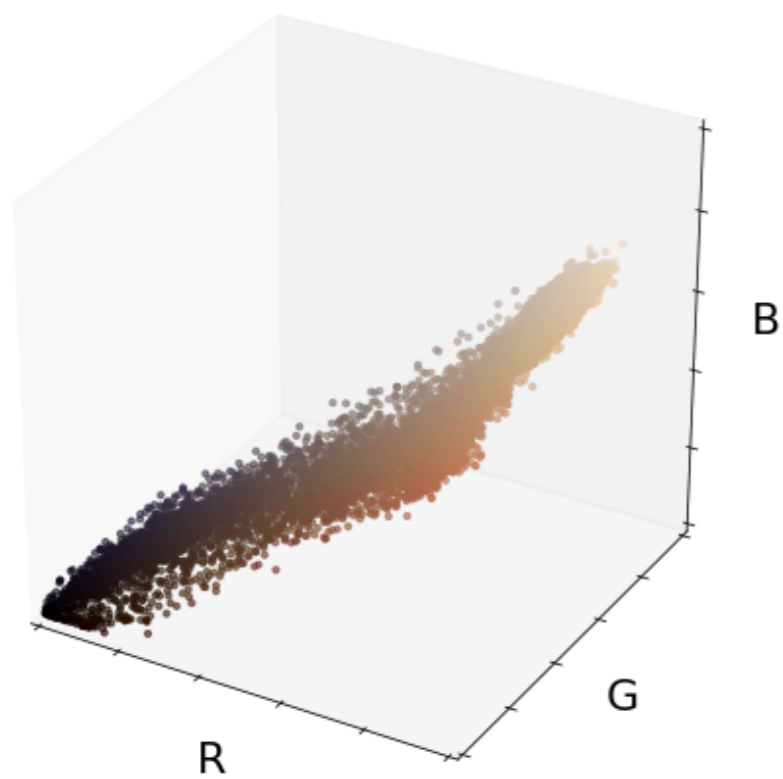


Color Transfer Map



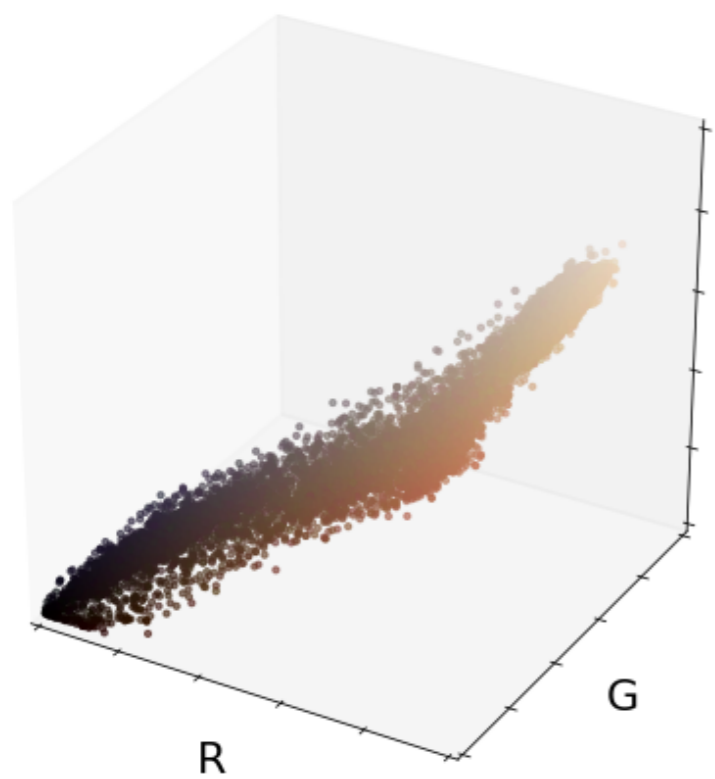


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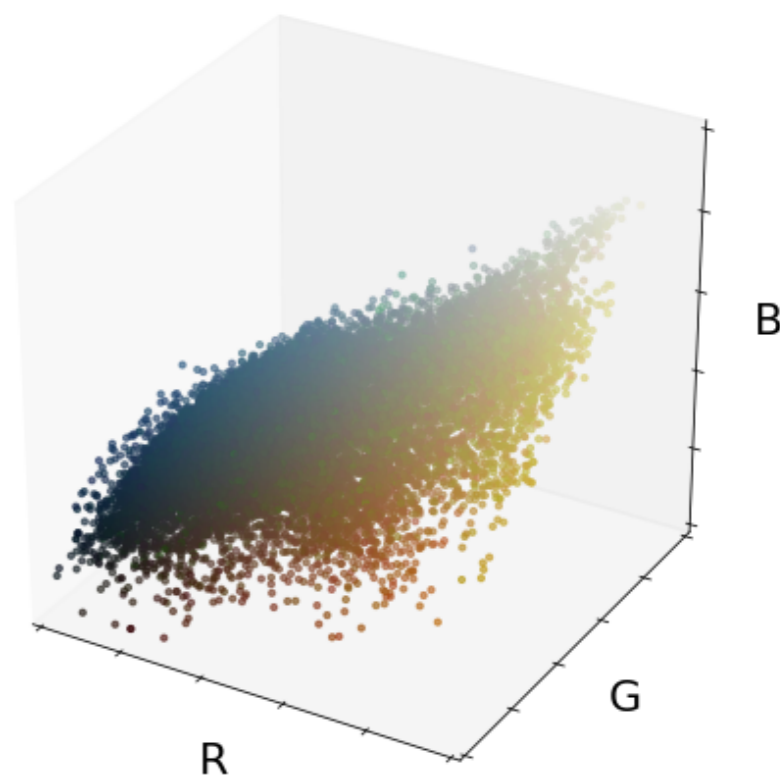


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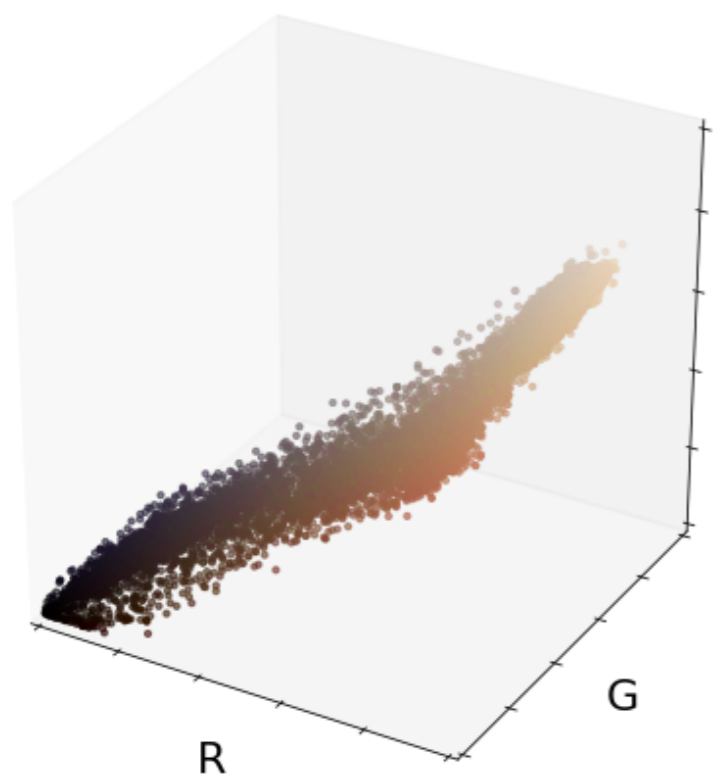
B

Matching



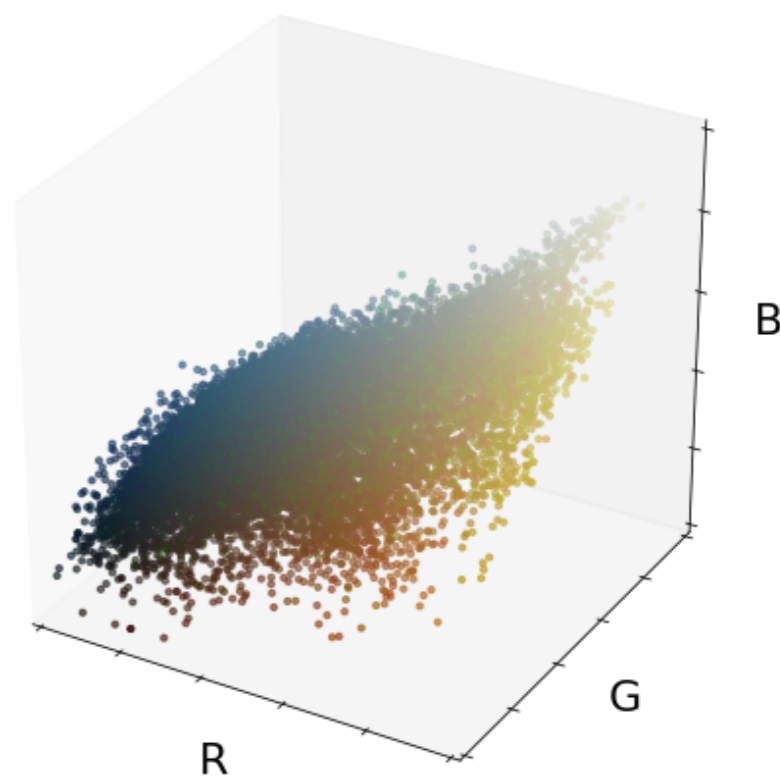


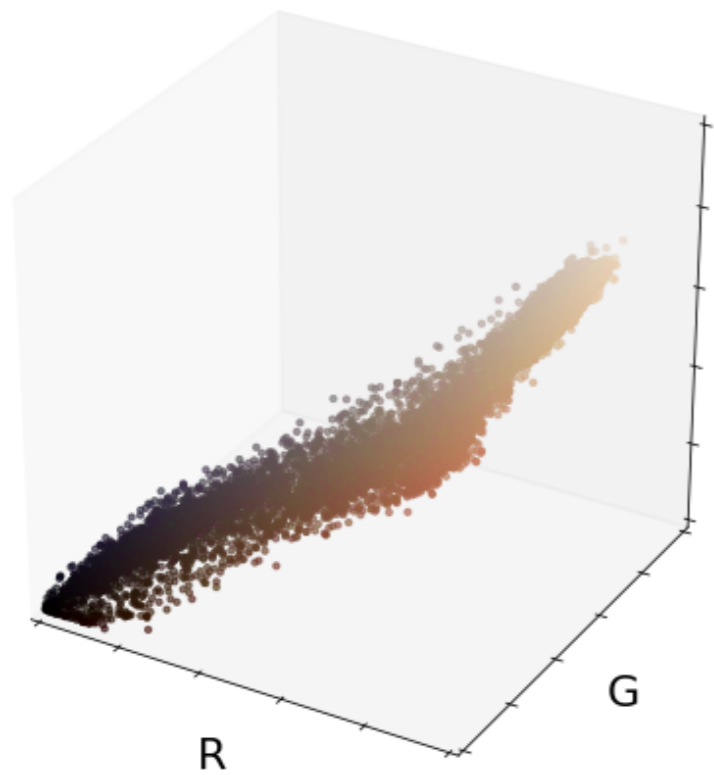
Color Transfer Map



B

Matching





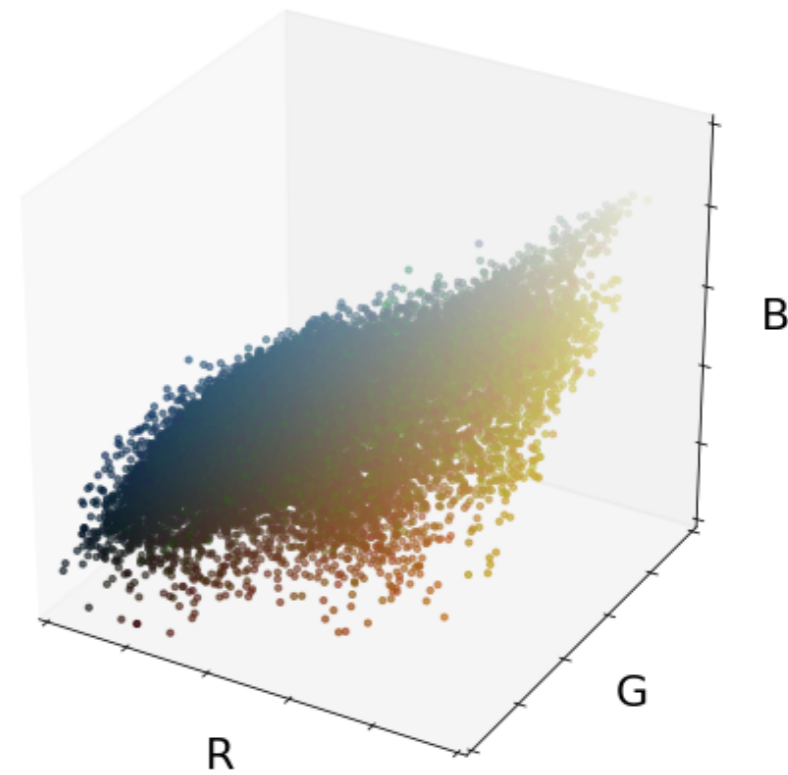
x_1, \dots, x_n

B

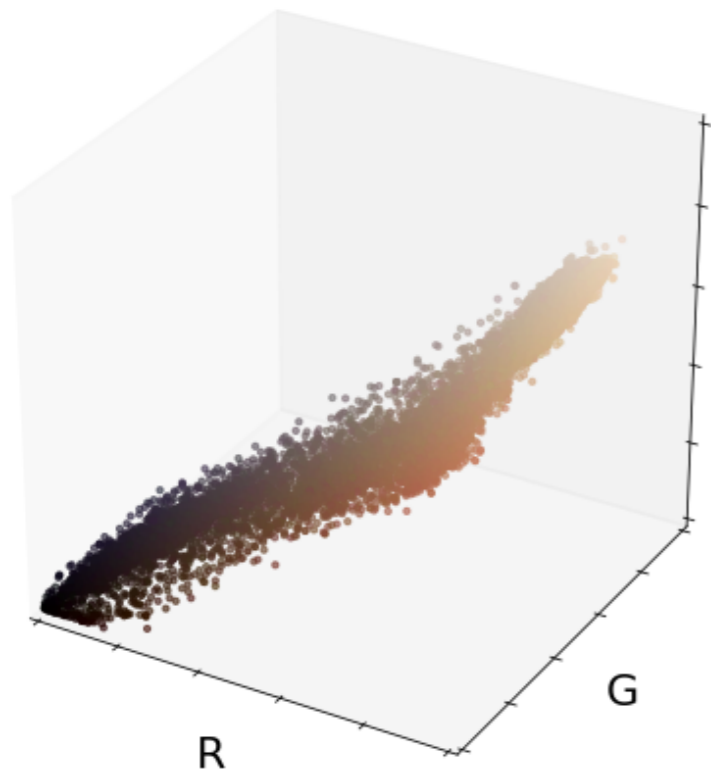
Matching



$\sigma \in \mathcal{S}_n$



y_1, \dots, y_n



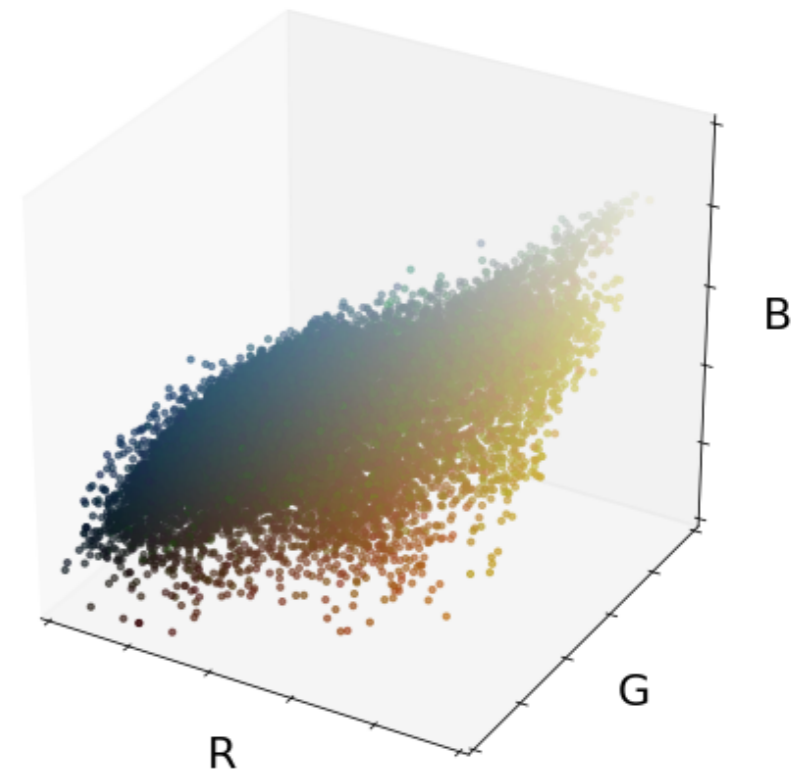
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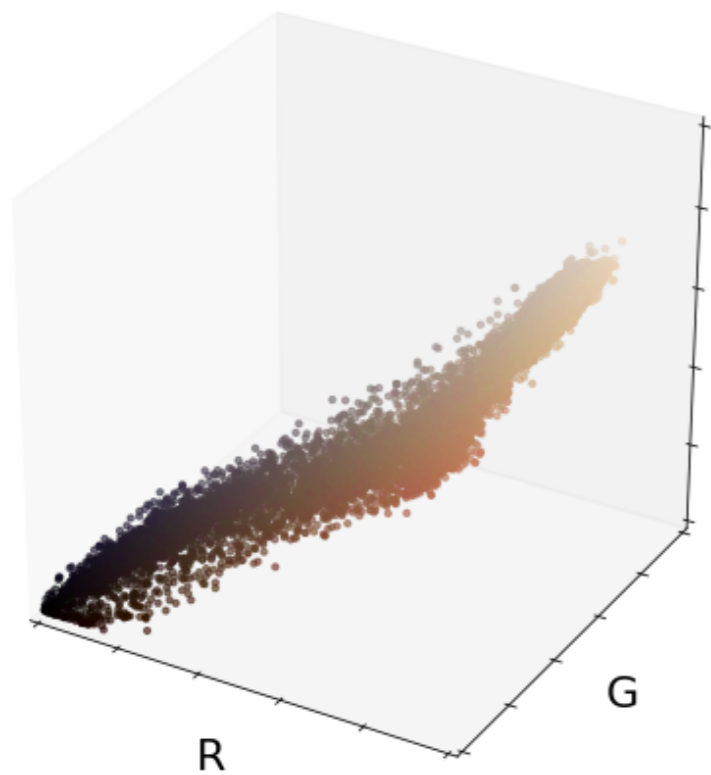


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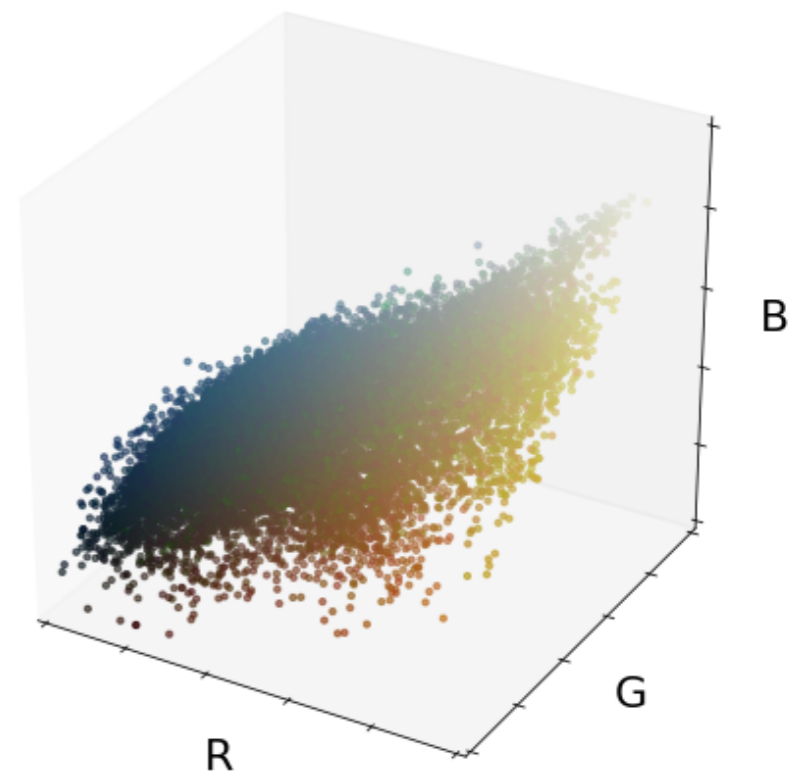
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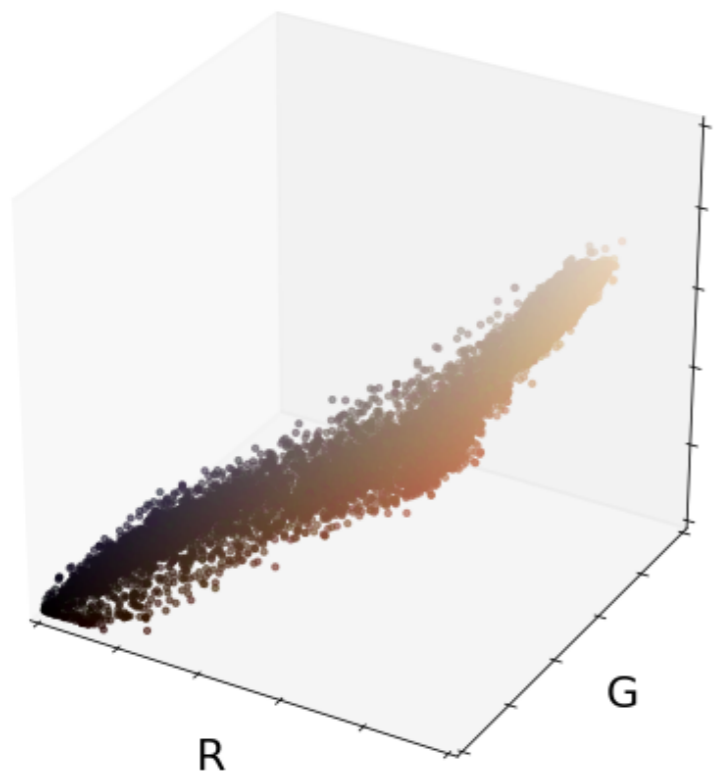


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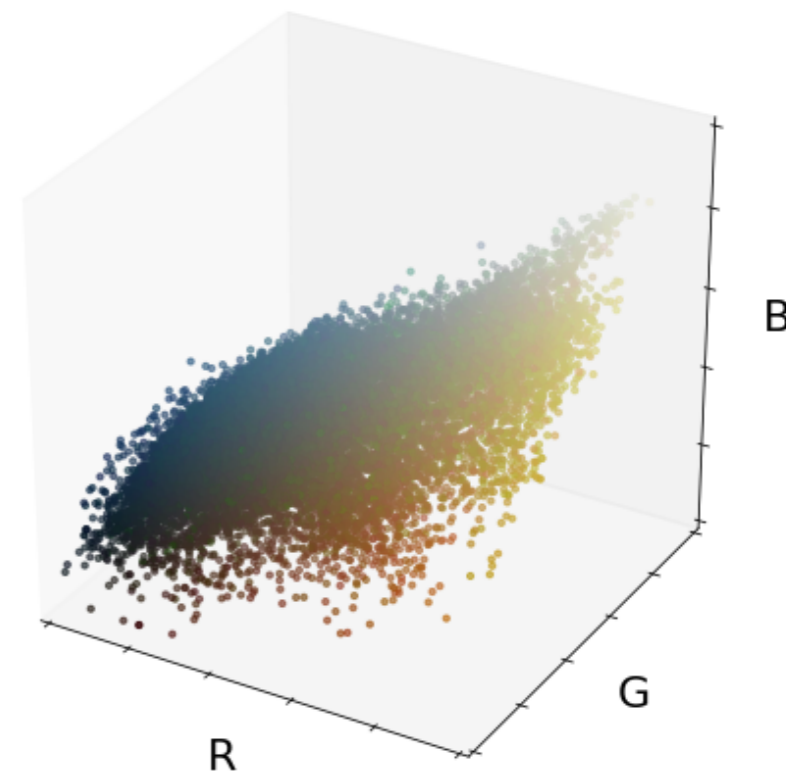
$$\|x_i - y_{\sigma(i)}\|^2$$



x_1, \dots, x_n

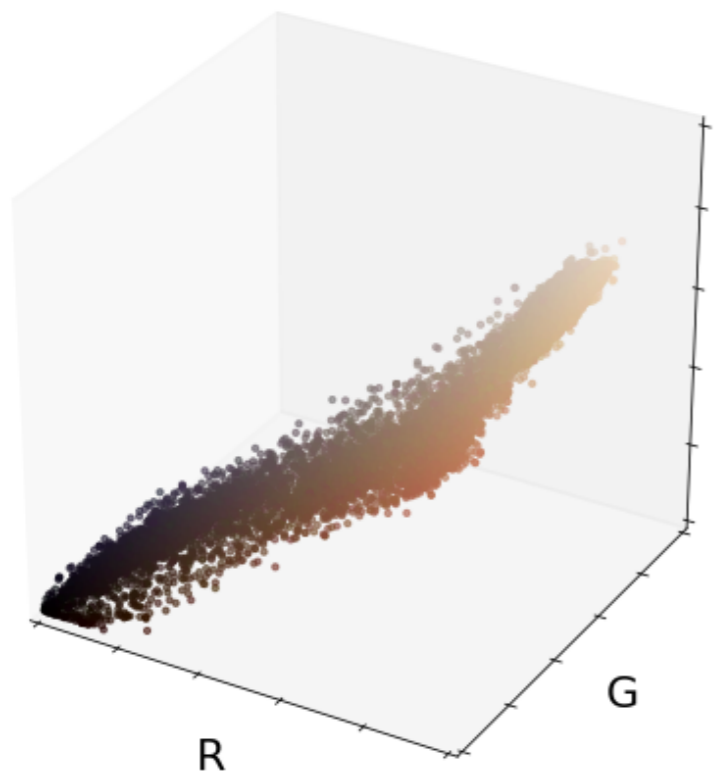
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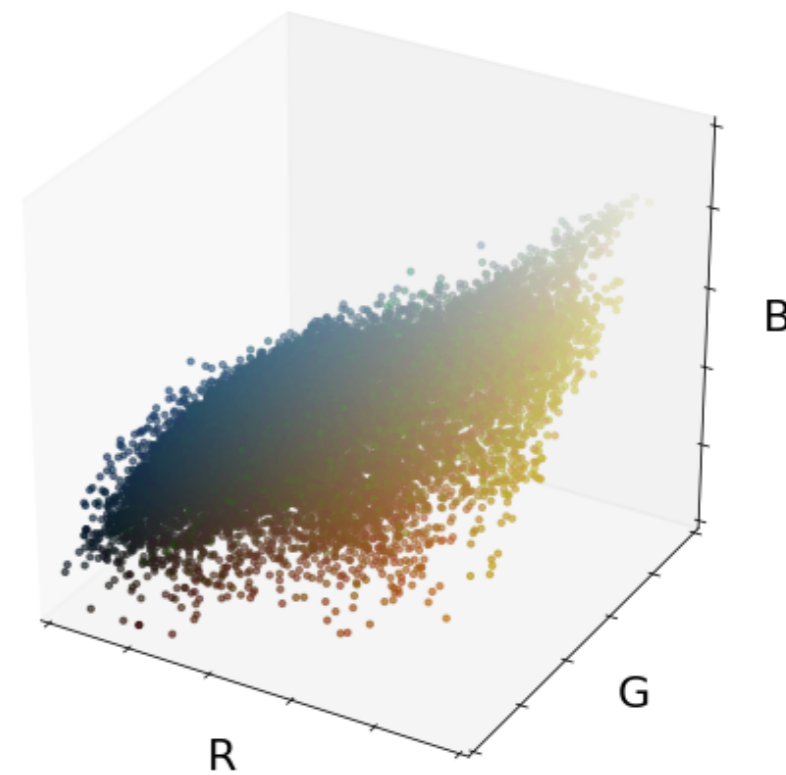
$$\sum_{i=1}^n \|x_i - y_{\sigma(i)}\|^2$$



x_1, \dots, x_n

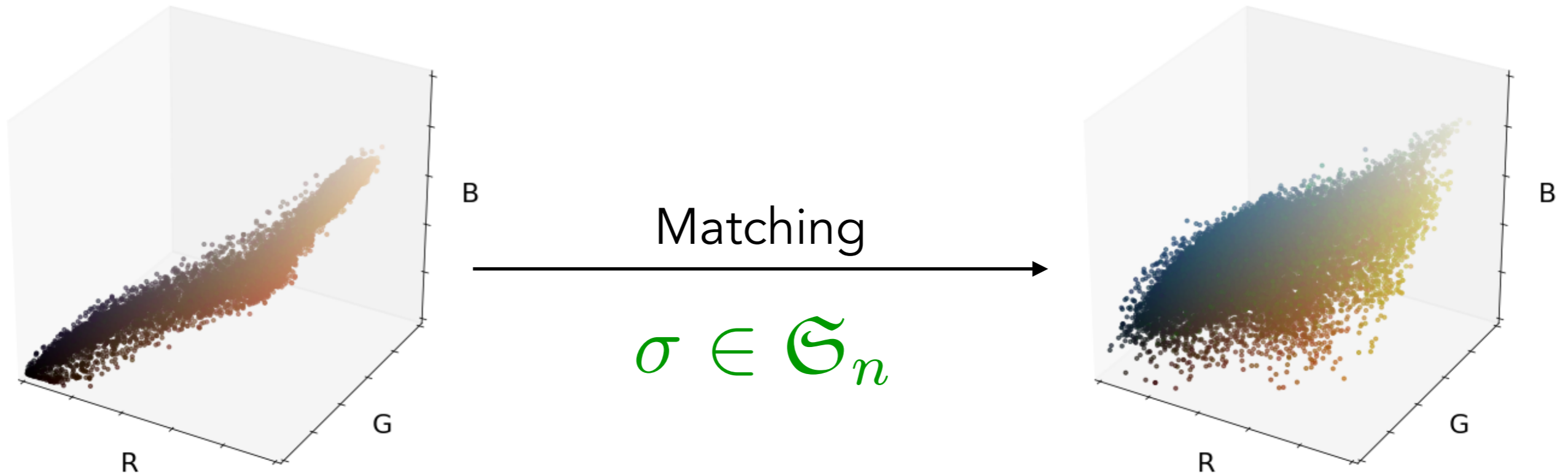
Matching

$\sigma \in \mathfrak{S}_n$



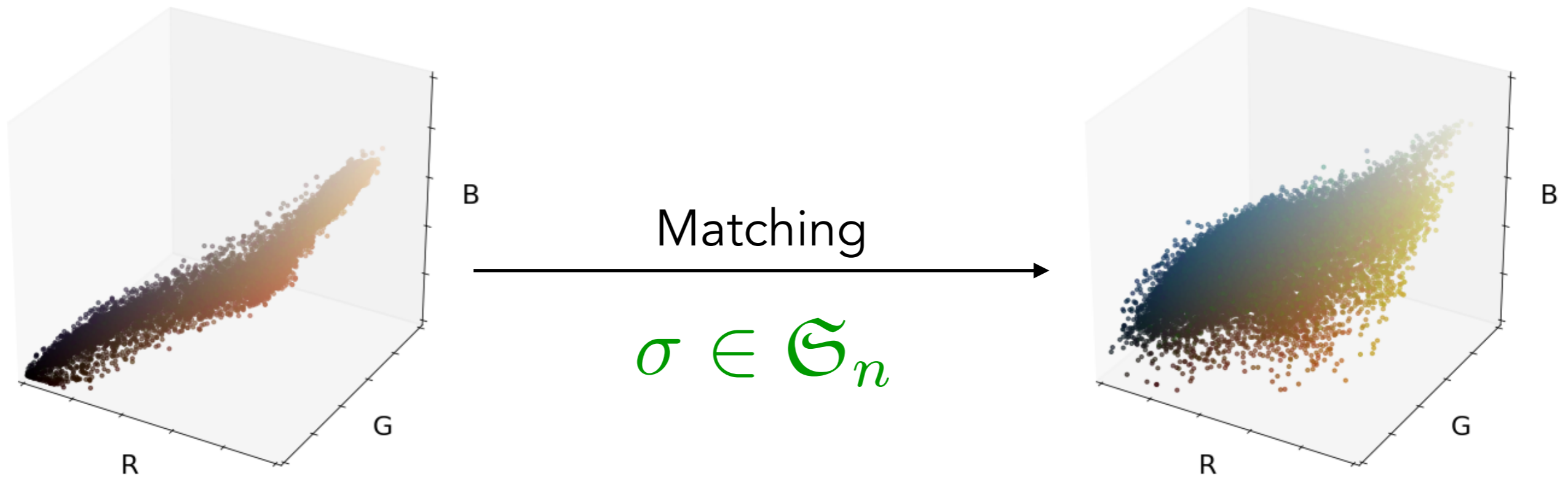
y_1, \dots, y_n

$$\min_{\sigma \in \mathfrak{S}_n} \sum_{i=1}^n \|x_i - y_{\sigma(i)}\|^2$$



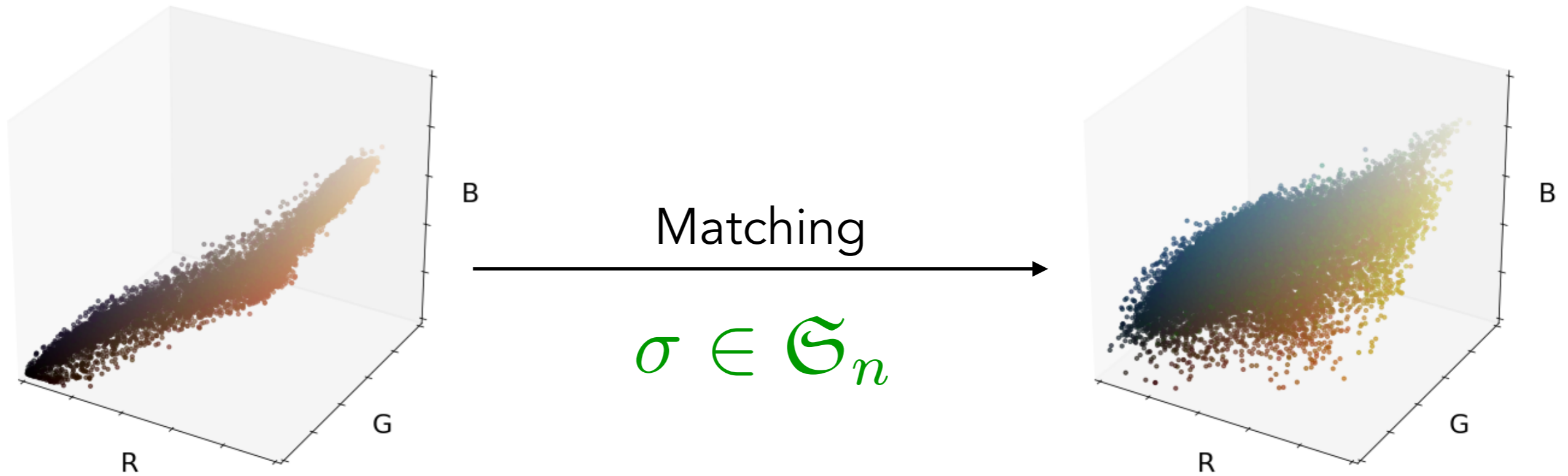
Discrete Monge Problem (1781)

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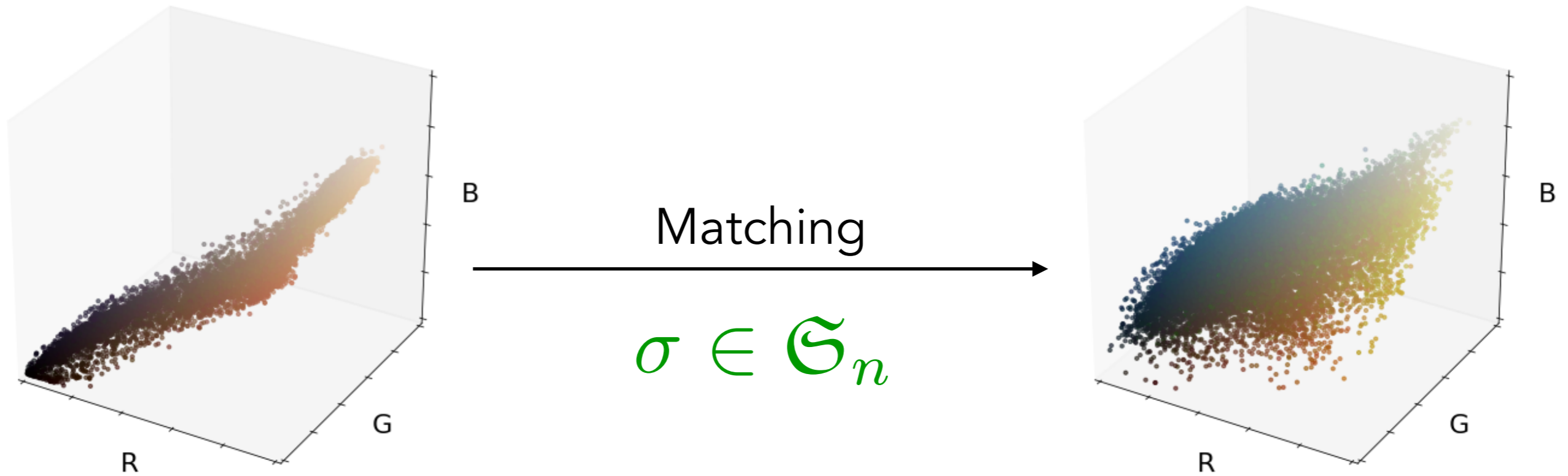
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- (i) How to handle repeated points ?
- (ii) How to handle different numbers of points ?
- (iii) How to compute this combinatorial problem ?

OPTIMAL TRANSPORT

$$\min_{\sigma \in \mathfrak{S}_n} \sum_{i=1}^n \|x_i - y_{\sigma(i)}\|^2$$

$$\min_{\sigma \in \mathfrak{S}_n} \sum_{i=1}^n \sum_{j=1}^n \|x_i - y_j\|^2 \mathbb{1}_{\sigma(i)=j}$$

$$\min_{P \in \mathfrak{P}_n} \sum_{i=1}^n \sum_{j=1}^n \|x_i - y_j\|^2 P_{ij}$$

$$\mathfrak{P}_n = \{P \in \mathbb{R}^{n \times n} \text{ permutation matrix}\}$$

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If $\mathbf{a} \in \mathbb{R}^n$, $\mathbf{b} \in \mathbb{R}^m$ are probability weights, we define the associated **transportation polytope**:

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$$\mathcal{U}(\mathbf{a}, \mathbf{b}) = \{P \in \mathbb{R}_+^{n \times m} \mid P \mathbf{1}_m = \mathbf{a}, P^\top \mathbf{1}_n = \mathbf{b}\}$$

Discrete Kantorovitch Problem

$$W_2^2(\mu, \nu) = \min_{P \in \mathcal{U}(\mathbf{a}, \mathbf{b})} \sum_{i=1}^n \sum_{j=1}^m \|x_i - y_j\|^2 P_{ij}$$

where $\mu = \sum_{i=1}^n \mathbf{a}_i \delta_{x_i}$ and $\nu = \sum_{j=1}^m \mathbf{b}_j \delta_{y_j}$ are probability measures

2-Wasserstein distance

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Why

should we

care?

Many applications in Machine Learning, some related to Astrophysics:

- Brenier et al., Reconstruction of the early Universe as a convex optimization problem 1999
- Wasserstein Dictionary Learning
- Computer Graphics
- Generative Models
- Model fitting (Minimum Kantorovich Estimators)

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$$T : \mathbb{R}^d \rightarrow \mathbb{R}^d$$

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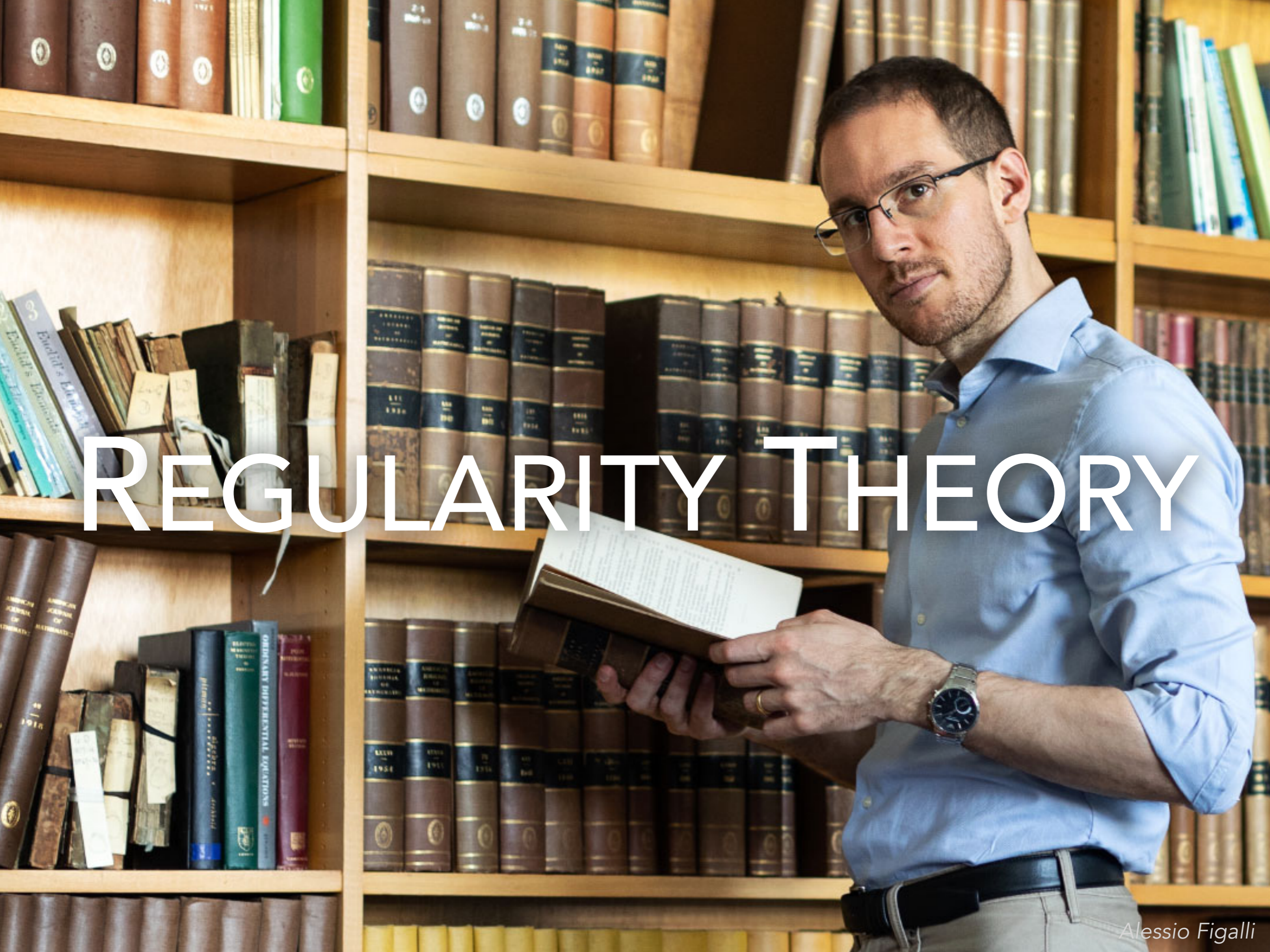
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$$X \sim \mu \implies T(X) \sim \nu$$



REGULARITY THEORY

Let μ and ν be two probability measures over \mathbb{R}^d .

$$\inf_{T_{\#}\mu=\nu} \int \|x - T(x)\|^2 d\mu(x)$$

When does the Monge problem admit a solution ?

What can be said about it ?

Let μ and ν be two probability measures over \mathbb{R}^d .

$$\inf_{T_{\#}\mu=\nu} \int \|x - T(x)\|^2 d\mu(x)$$

Brenier Theorem

1. If μ is *absolutely continuous* with respect to the Lebesgue measure, the Monge problem admits a unique solution
2. If the Monge problem admits a solution T , then there exists a convex function f , called a **Brenier potential**, s.t.

$$T = \nabla f$$

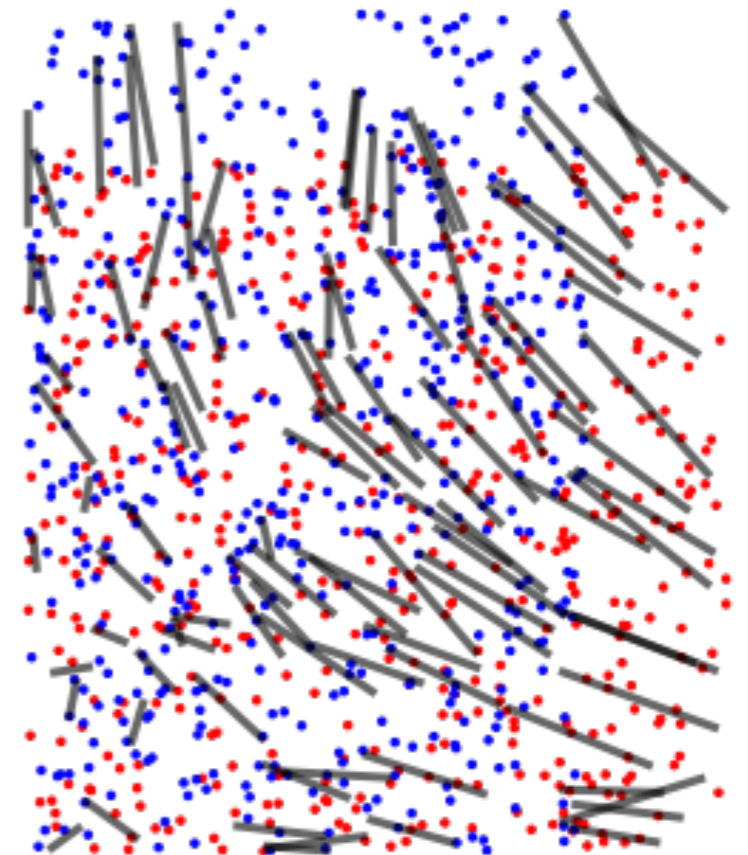
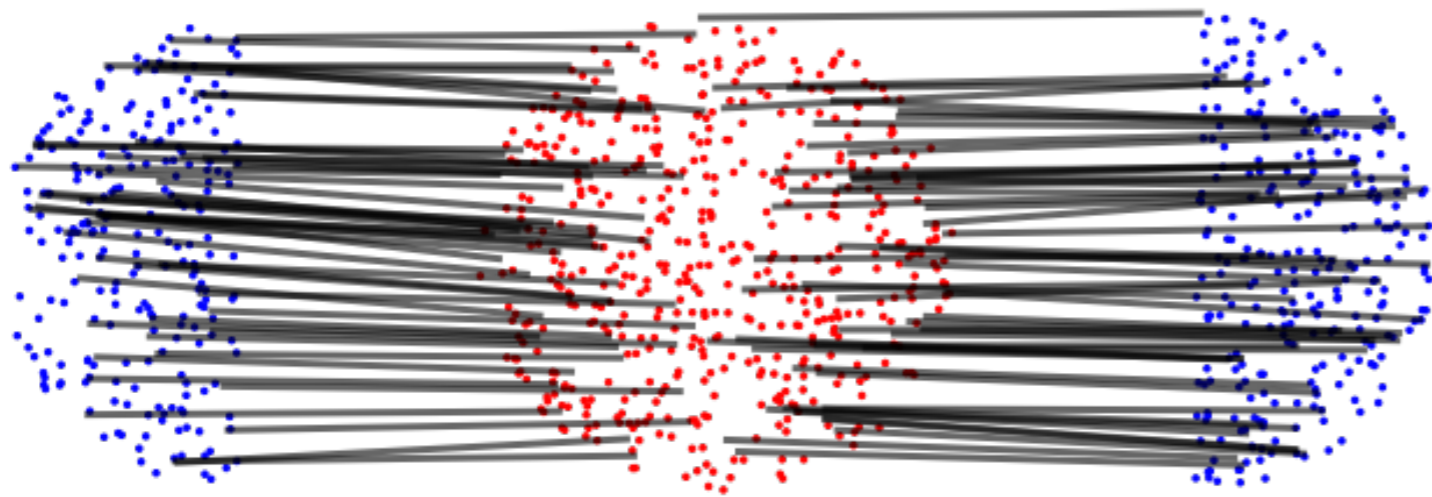
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Instead of finding assumptions under which the optimal map exists and exhibits some regularity, we will enforce such regularity directly in the OT problem.



SMOOTH AND STRONGLY CONVEX BRENIER POTENTIALS





$$\ell \|x - y\| \leq \|\nabla f(x) - \nabla f(y)\| \leq L \|x - y\|$$



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We ask that $T = \nabla f$ is a bi-Lipschitz map



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$$\hookrightarrow f \in \mathcal{F}_{\ell, L}$$

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Instead, we will try to best approximate ν as a push-forward of μ through a regular map:

$$\min_{f \in \mathcal{F}_{\ell, L}} W_2 [\nabla f_\# \mu, \nu]$$

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Smooth and Strong Convex

Brenier Potentials

Even when the measures are discrete, this is a *infinite dimensional* optimization problem !

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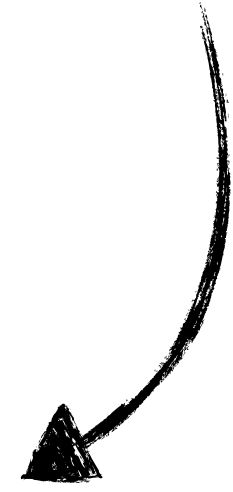
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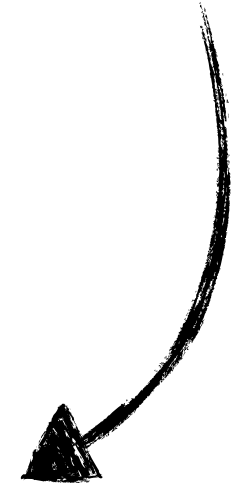
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$$\min_{f \in \mathcal{F}_{\ell, L}} W_2 [\nabla f \# \mu, \nu]$$

$$\min_{\substack{z_1, \dots, z_n \in \mathbb{R}^d \\ u \in \mathbb{R}^n}} W_2^2 \left(\sum_{i=1}^n a_i \delta_{z_i}, \nu \right)$$


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$$u_i \geq u_j + \langle z_j, x_i - x_j \rangle$$

$$+ \frac{1}{2(1 - \ell/L)} \left(\frac{1}{L} \|z_i - z_j\|^2 + \ell \|x_i - x_j\|^2 - 2 \frac{\ell}{L} \langle z_j - z_i, x_j - x_i \rangle \right)$$

$$x_1, \dots, x_n \sim \mu$$

$$\hat{\mu}_n = \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$$

$$y_1, \dots, y_n \sim \nu$$

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We can easily compute the map on any new point x by solving a cheap QCQP

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$$\min_{v \in \mathbb{R}, g \in \mathbb{R}^d} v$$

$$\text{s.t. } \forall i, v \geq u_i + \langle z_i^*, x - x_i \rangle$$

$$+ \frac{1}{2(1 - \ell/L)} \left(\frac{1}{L} \|g - z_i^*\|^2 + \ell \|x - x_i\|^2 - 2 \frac{\ell}{L} \langle z_i^* - g, x_i - x \rangle \right)$$

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This defines an estimator ∇f^* of the optimal transport map sending μ to ν

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We define the *SSNB estimator* as a plug-in:

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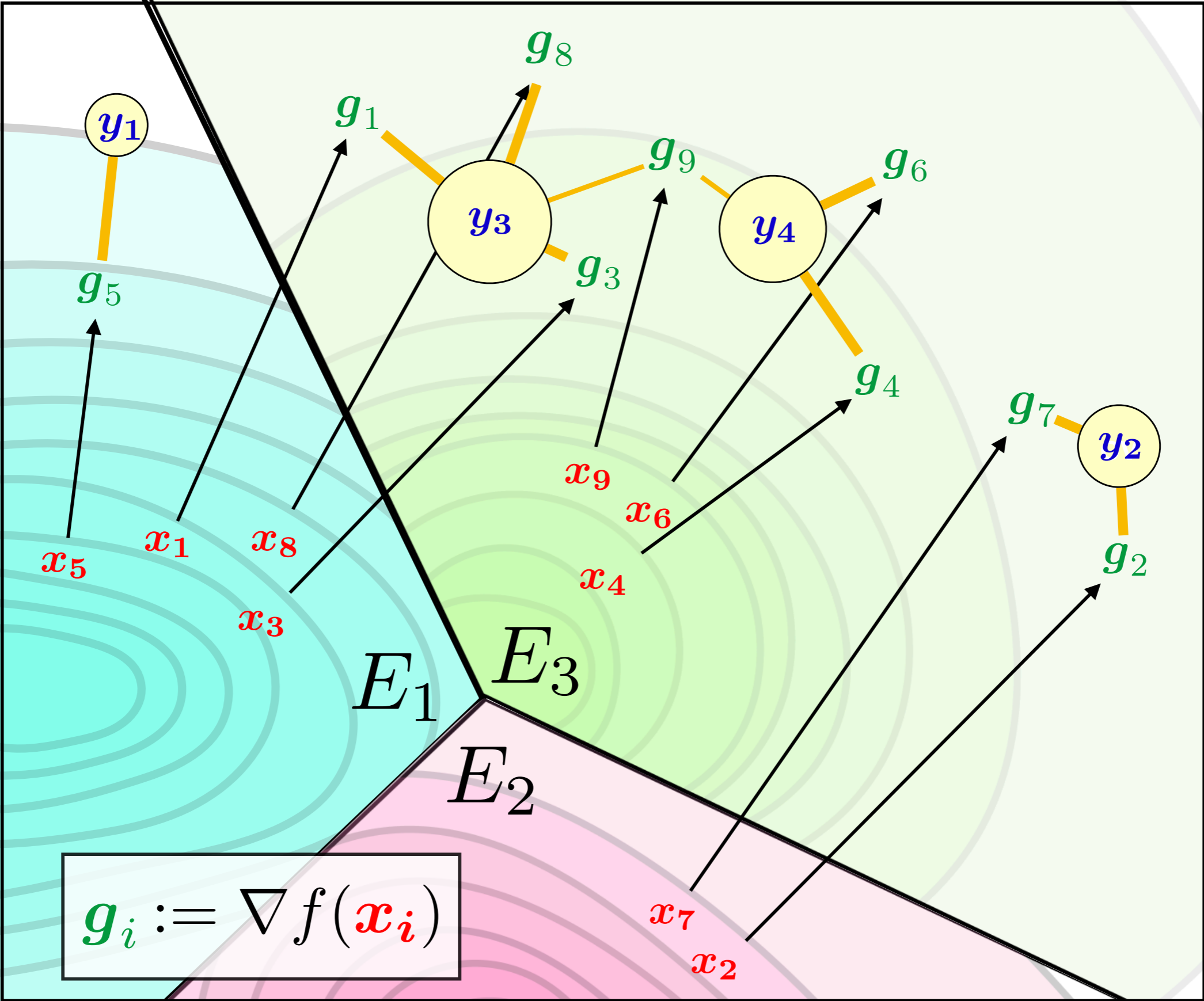
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Regularity "by part"



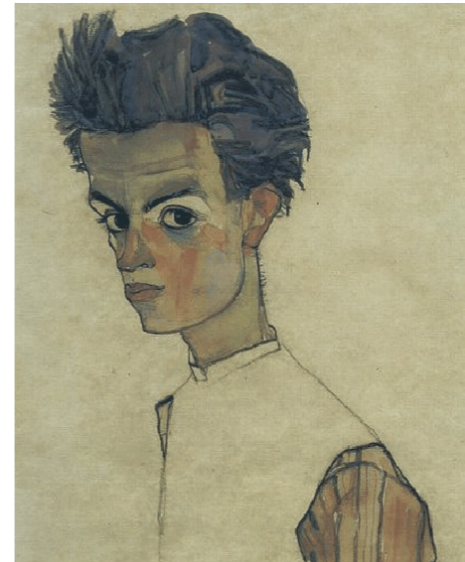


$\ell = 0$

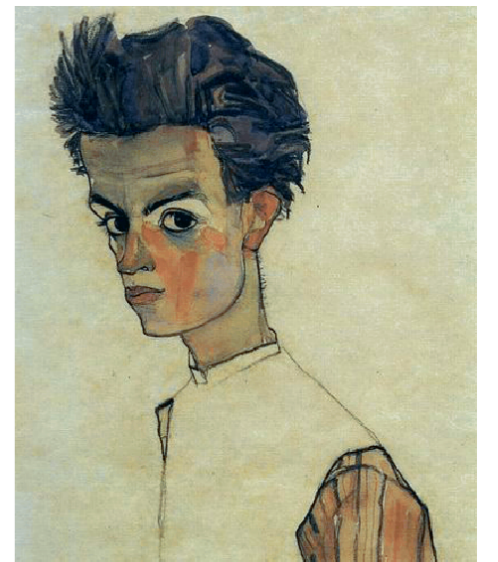
$\ell = 0.5$

$\ell = 1$

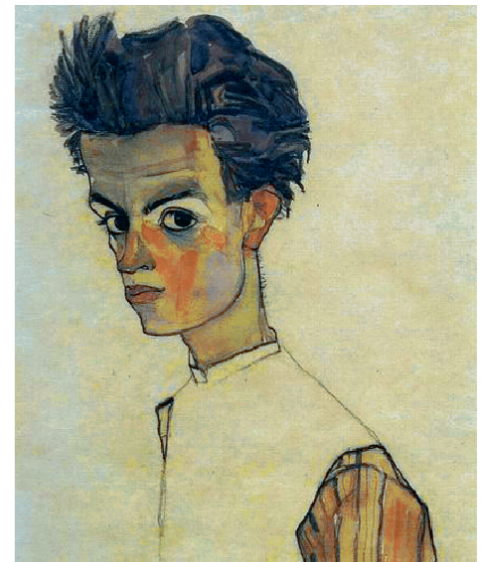
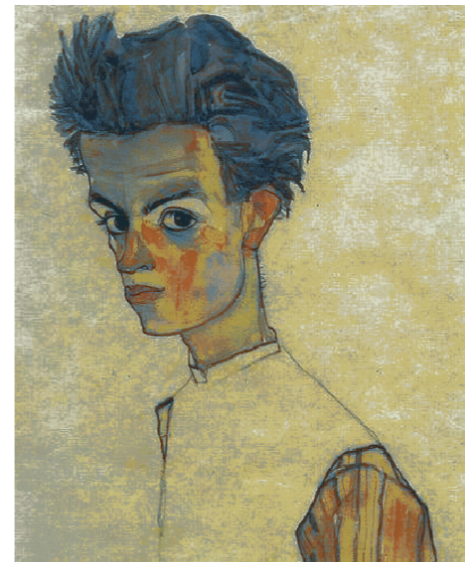
$L = 1$



$L = 2$



$L = 5$





QUESTIONS ?